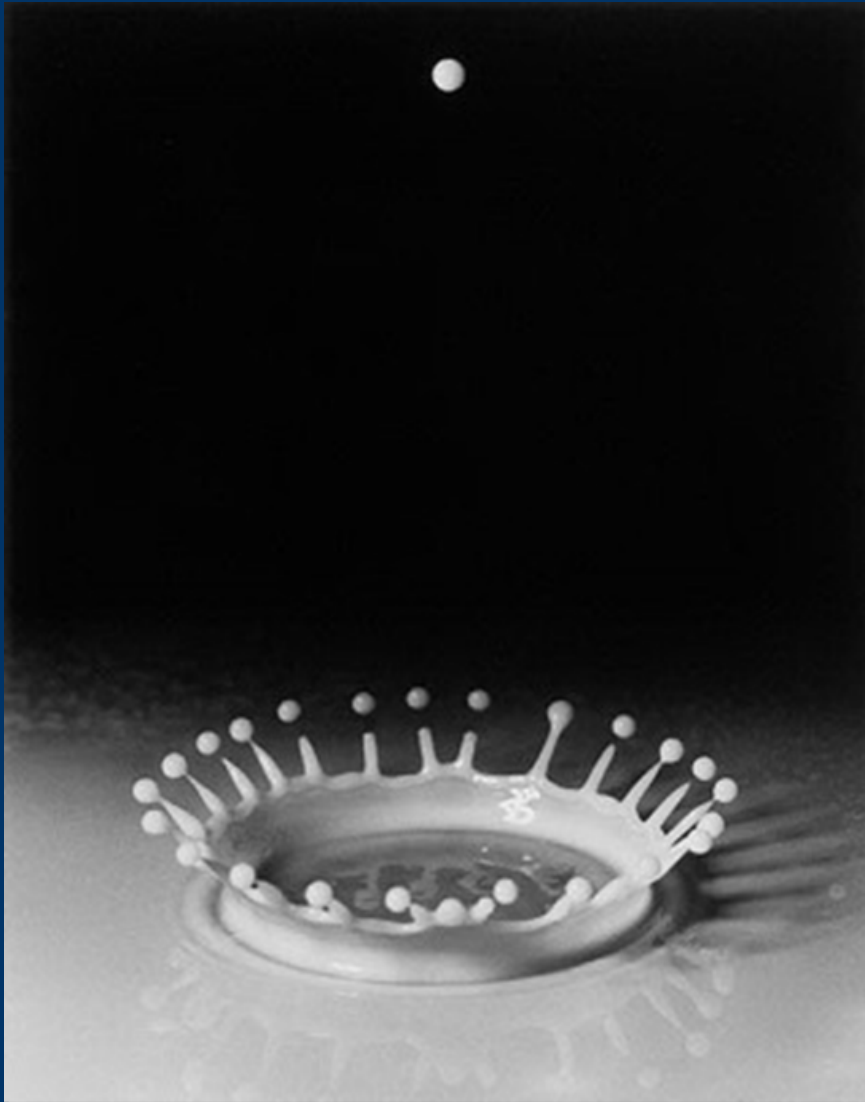


Camera Culture

Course WebPage :
<http://raskar.info/course.html>



Harold 'Doc' Edgerton 1936

Today's Plan

- Summary, 'Camera in 10 years'
- Next class big question:
 - 'Camera for better Image Search'
- Understanding Camera Constraints
 - Camera Parameters
 - Solutions

- Homework

- What will a camera look like in 10 years, 20 years?
- What will be the dominant platform and why?

Next Class

- Homework
 - How can we augment the camera to support best 'image search'?
 - Search=segment/identify/recognize/transform/compare/archive
 - How can we make the visual experience machine readable? Is this the key problem? 3D reconstruction? Hardware and software solutions? Crowdsourcing? Metadata tagging?
 - Material index/Segmentation/Repeatable view and illumination invariance/
 - Email to [raskar@media.mit.]
- Volunteer
 - Class notes
 - Select/read/present/paper
 - Visual Social Computing
 - Beyond Visible Spectrum
 - Mobile Photography
 - Emerging sensors
 - [Send me email ..]
 - (Extra Credit)

Topics

- Imaging Devices, Modern Optics and Lenses
- Emerging Sensor Technologies
- Mobile Photography
- Visual Social Computing and Citizen Journalism
- Imaging Beyond Visible Spectrum
- Computational Imaging in Sciences
- Trust in Visual Media
- Solutions for Visually Challenged
- Cameras in Developing Countries
- Future Products and Business Models

Topics

- Other courses
 - Art and Photography
 - CSAIL: Computational Photography
 - MechE: Optics
- Fall'2008
 - 'Intro to Computational Camera and Photography'
 - I will teach course in Fall
- Current course
 - More emphasis on future cameras
 - Faster review of technology and then look at impact/applications/opportunities
 - Big ideas/technologies/applications,
 - Understand rules-of-thumb and trade-offs
 - Ideal for thesis/projects/research papers/business models
 - Learn fun stuff before the nitty gritty

Jack Tumblin's Questions

- What does direct visual examination of an object give us that current photographs lack?
- What could we do to capture most of a photo's visually meaningful contents in machine-readable form?
- What is the best way to 'lash together' multiple photos of an object to form a unified visual archive?
- Museum Objects
 - How can we make a quick, low-cost, but complete archival record of a museum object?
 - Can we make such archives expandable? device-independent? View independent? Lighting-independent?
 - Can these archives help us find hidden object features? Search for similarities among large sets of objects?
 - Can they help us detect subtle long-term change & degradation of objects? Identify lost or stolen objects? Detect fakes?
 - What digital tools will help museum officials protect, share, and explore their collections with visitors?

Near Infrared Imaging



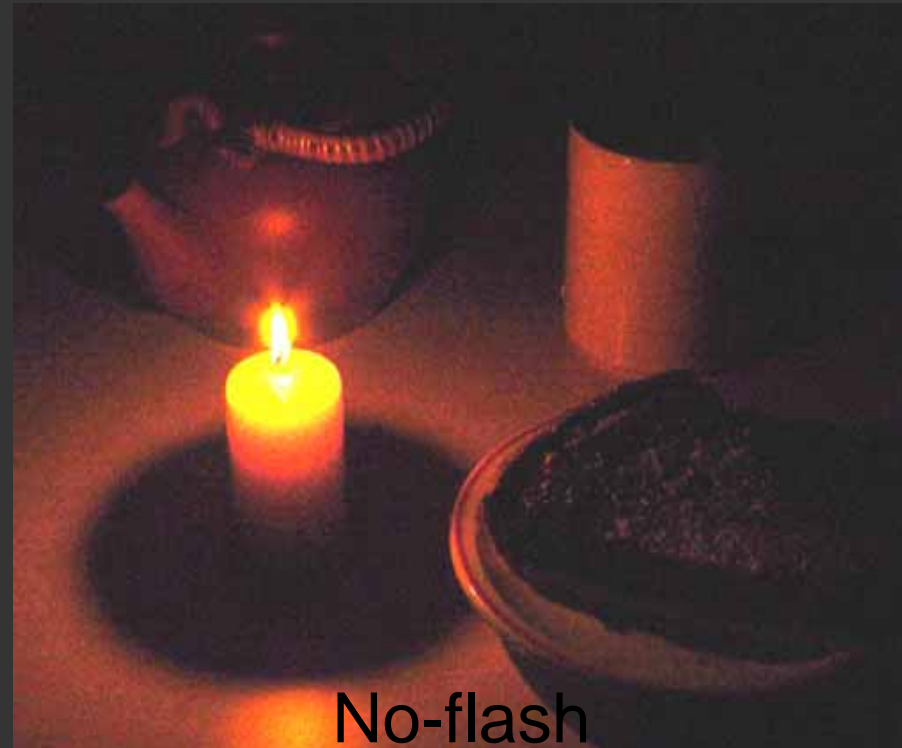
<http://www.hoagieshouse.com/IR>



<http://www.flickr.com/photos/mariusm/6333589/>

Illumination for Traffic Cameras

Photography: Full of Tradeoffs...



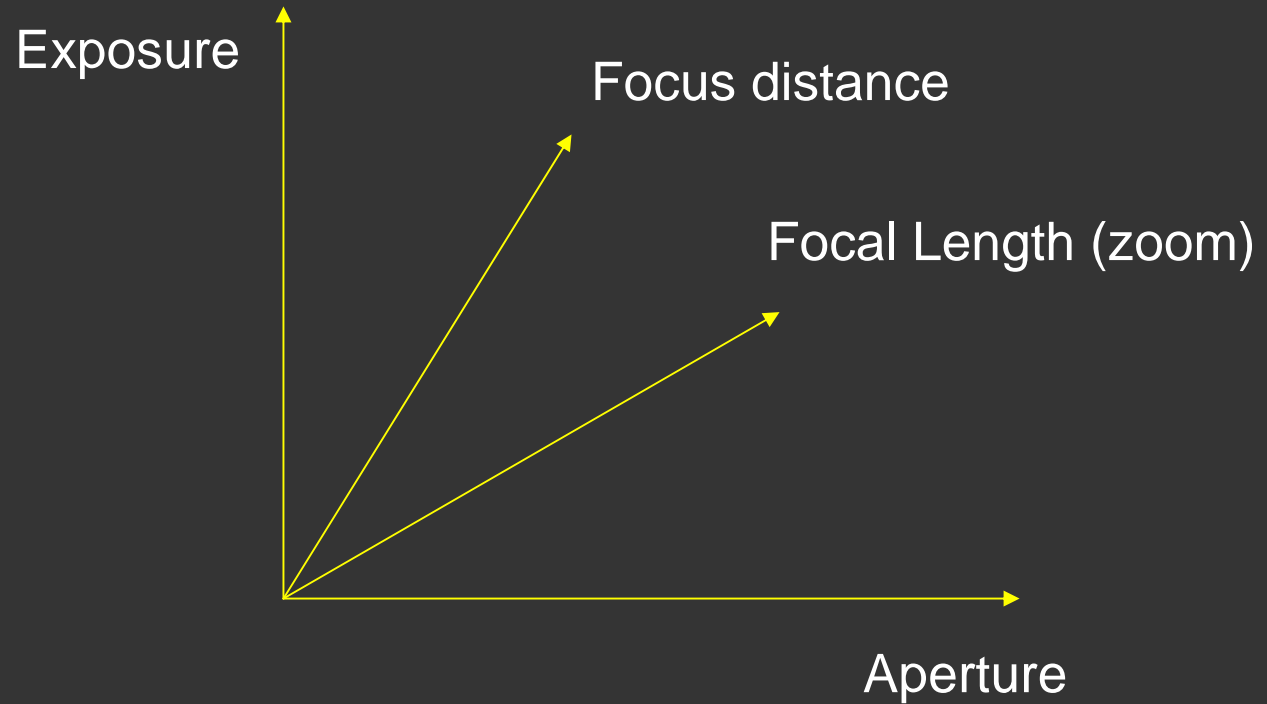
No-flash



Flash

- Available light vs. exposure time vs. scene movement vs. field of view vs. focus depth vs. sensitivity vs. noise vs. color rendition vs. color gamut vs. contrast vs. visible detail vs.

Available Light vs Parameter 'box'



Dynamic Range

Short Exposure



Goal: High Dynamic Range



Long Exposure

Processing: Very Long Exposure ?

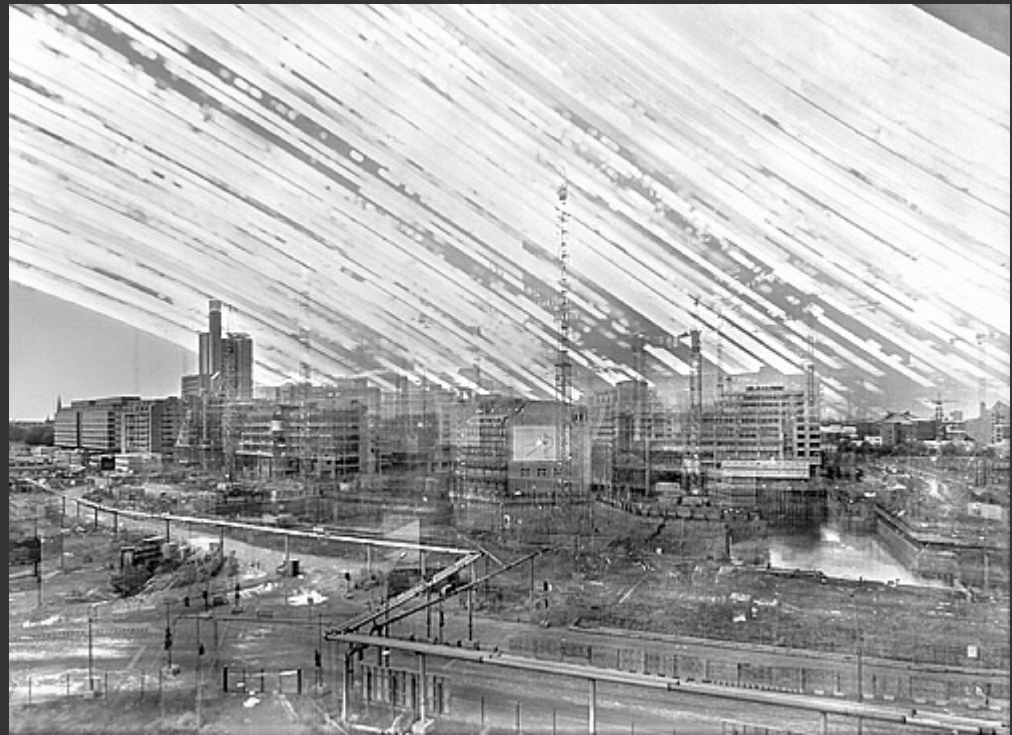
Michael Wesely: Open Shutter at The Museum of Modern Art

- http://www.wesely.org/moma.php?show_page=1
- http://www.moma.org/exhibitions/2004/Michael_Wesely_11-20-04.html



Postdamer Platz, Berlin

18 month long exposure



26 Month long exposure: Notice the sun tracks

High depth-of-field

- adjacent views use different focus settings
- for each pixel, select sharpest view [Haerberli90]



close focus

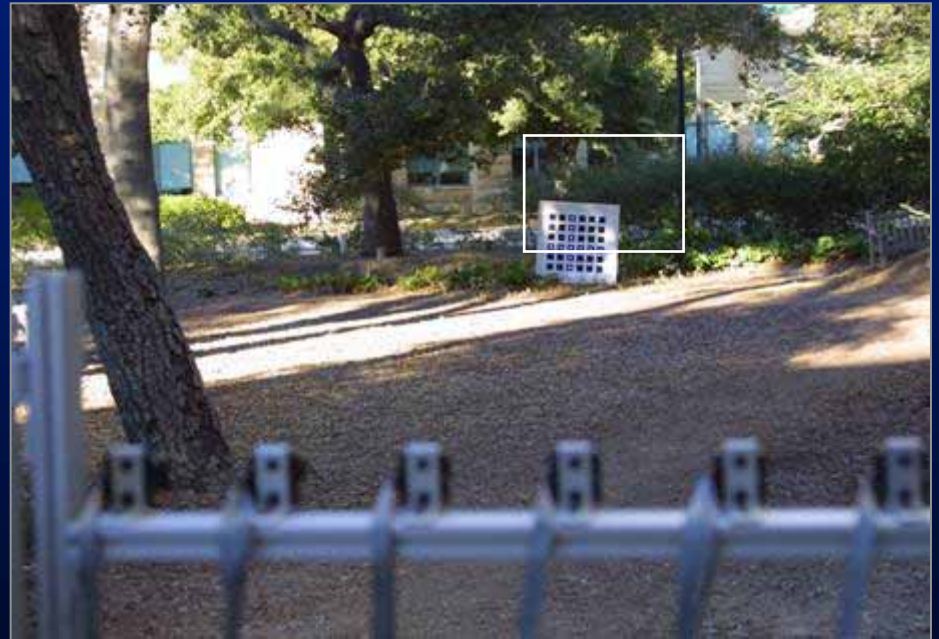
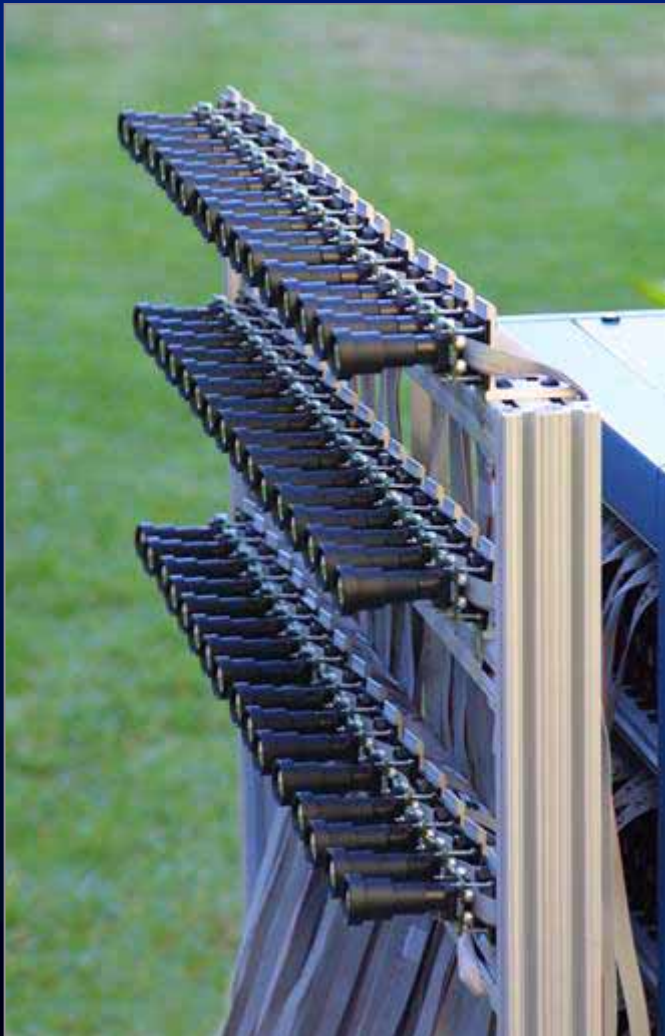


distant focus



composite

Long-range synthetic aperture photography



Levoy et al., SIGG2005

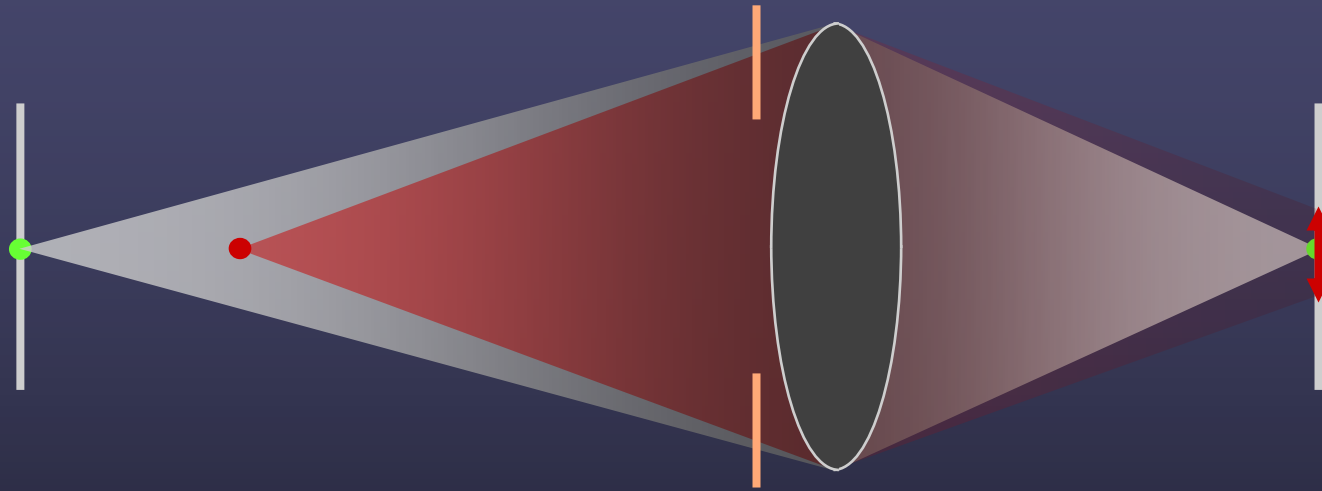
Synthetic aperture videography



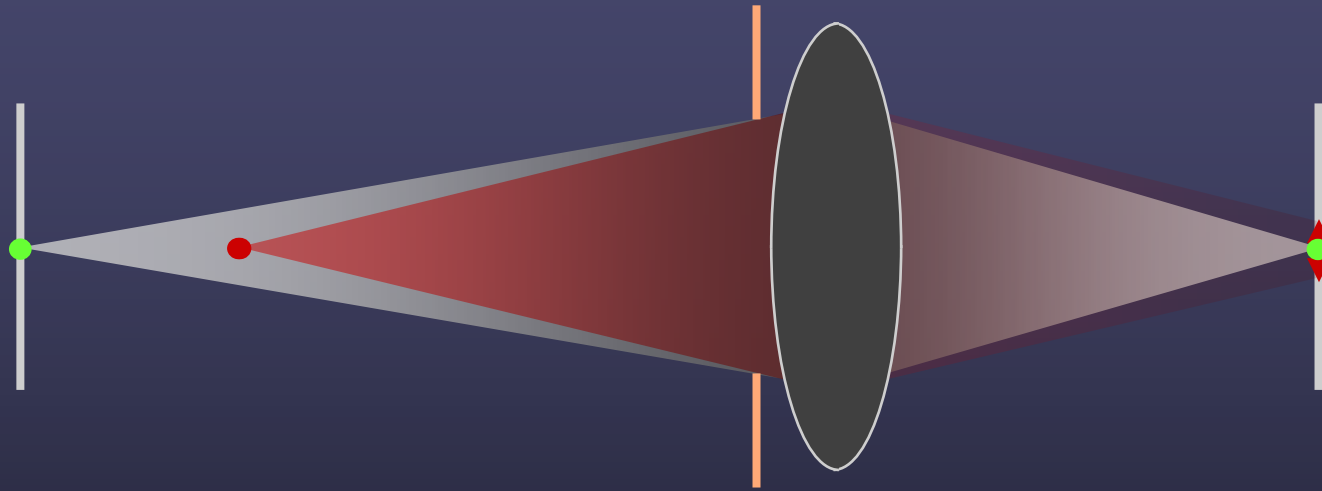
Focus Adjustment: Sum of Bundles



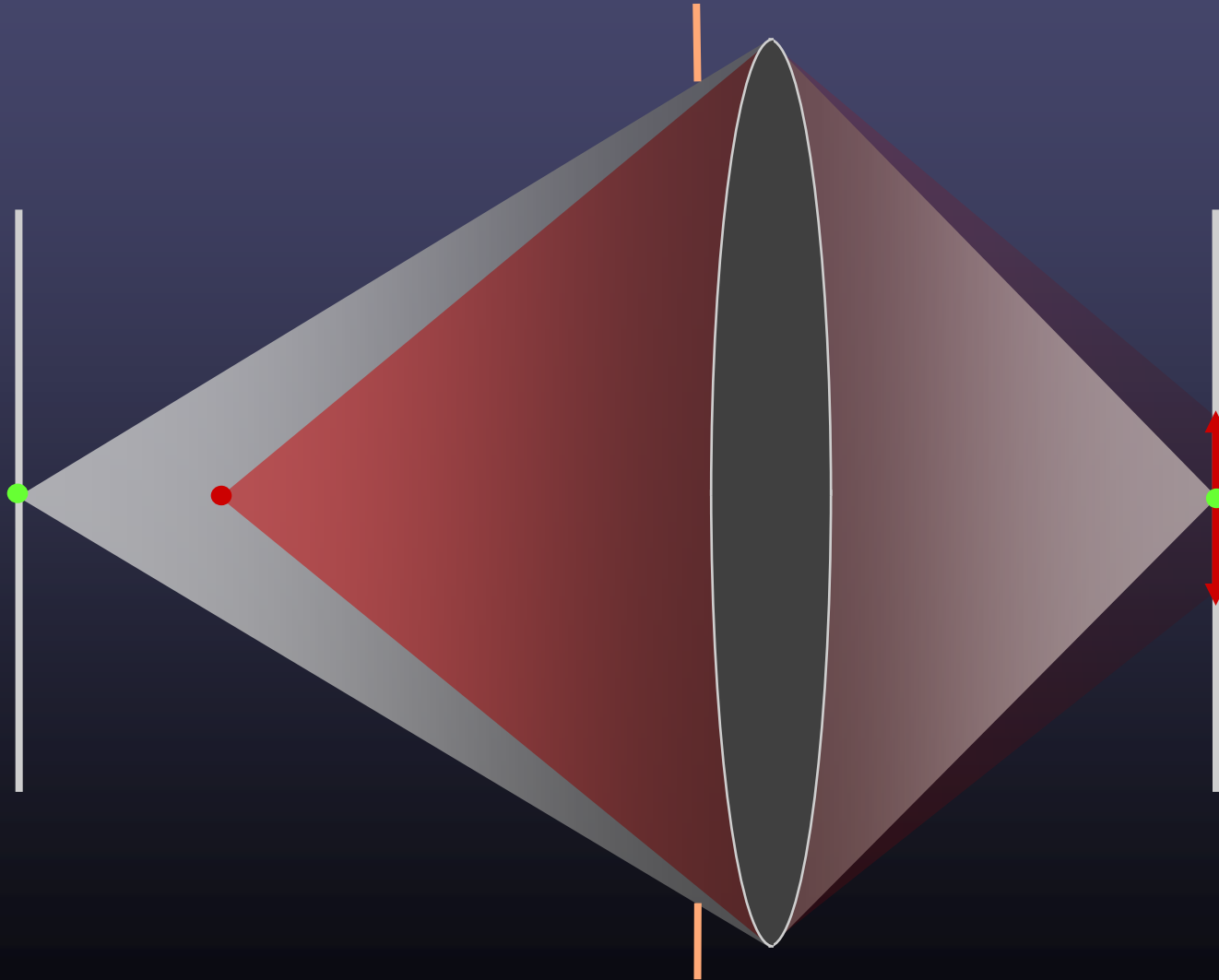
Synthetic aperture photography



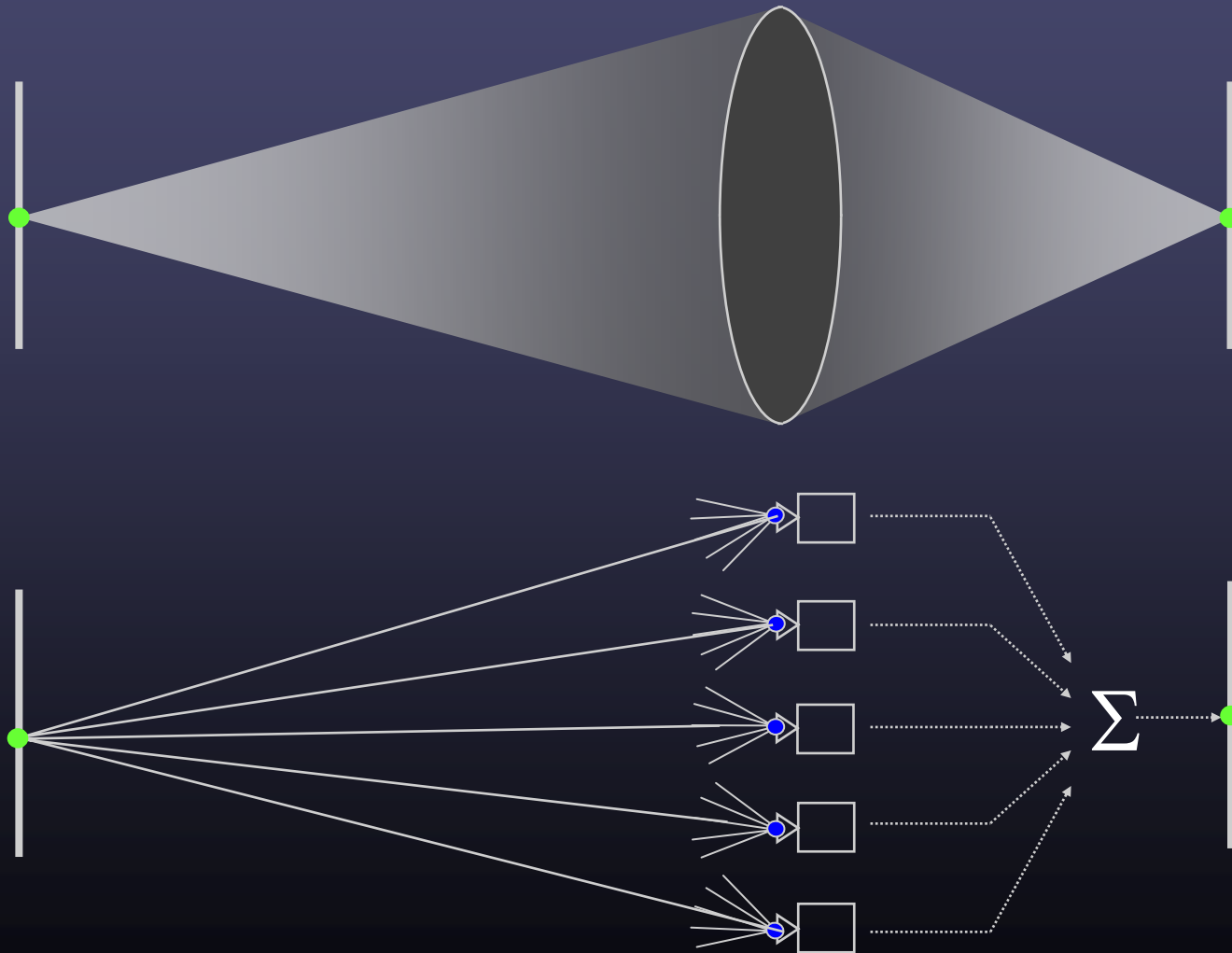
Synthetic aperture photography



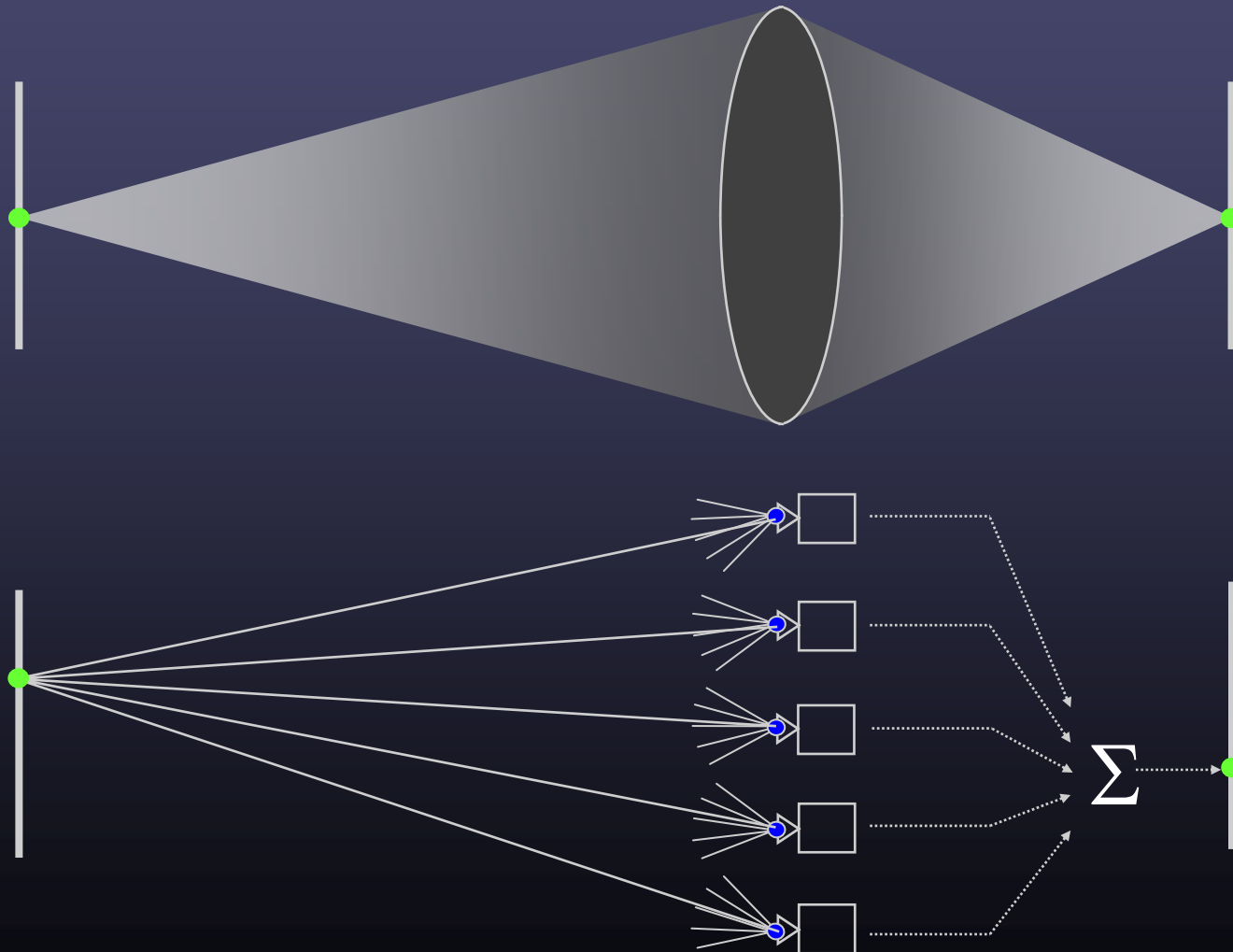
Synthetic aperture photography



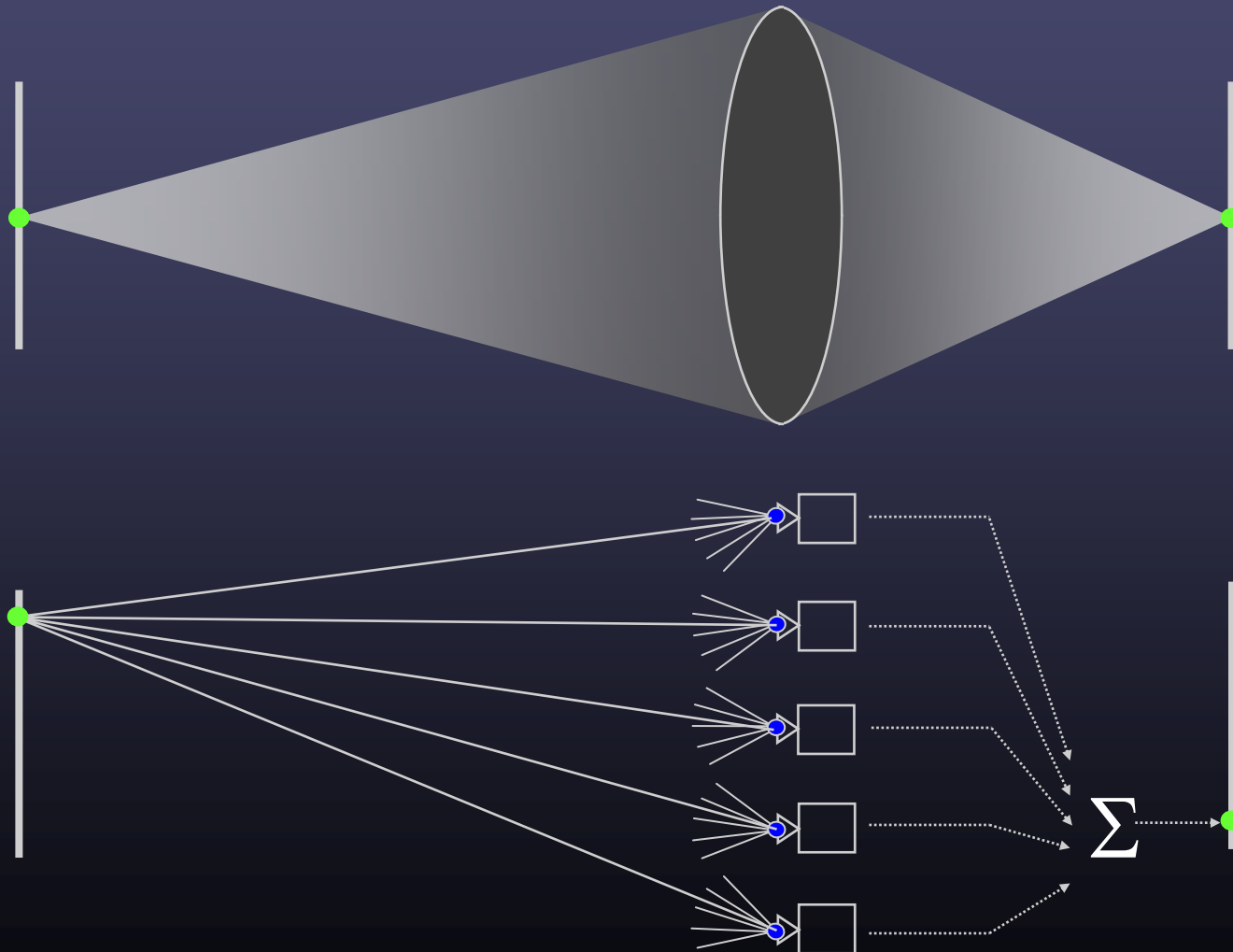
Synthetic aperture photography



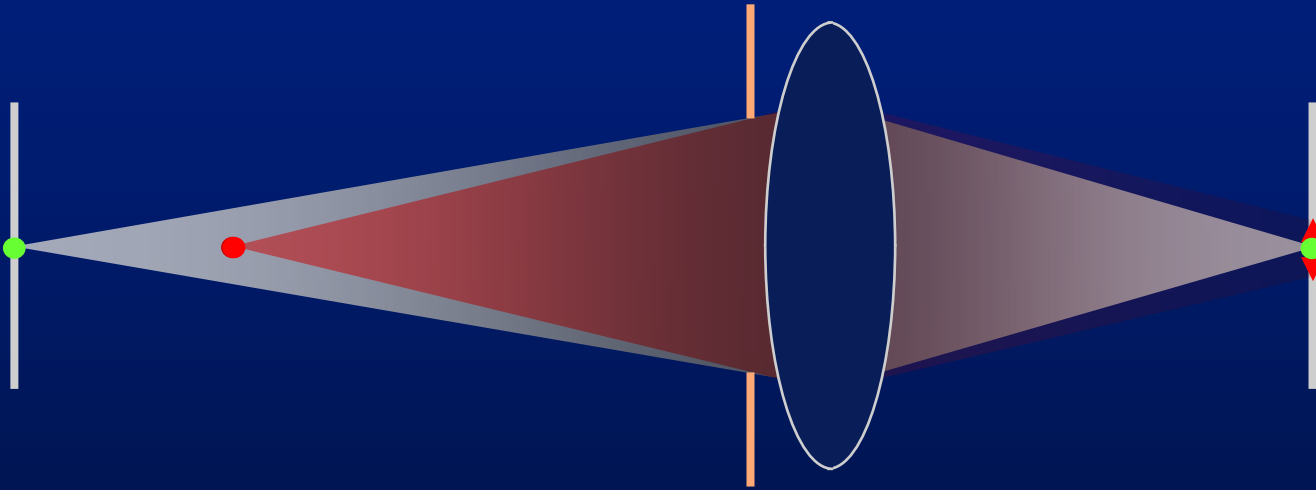
Synthetic aperture photography



Synthetic aperture photography



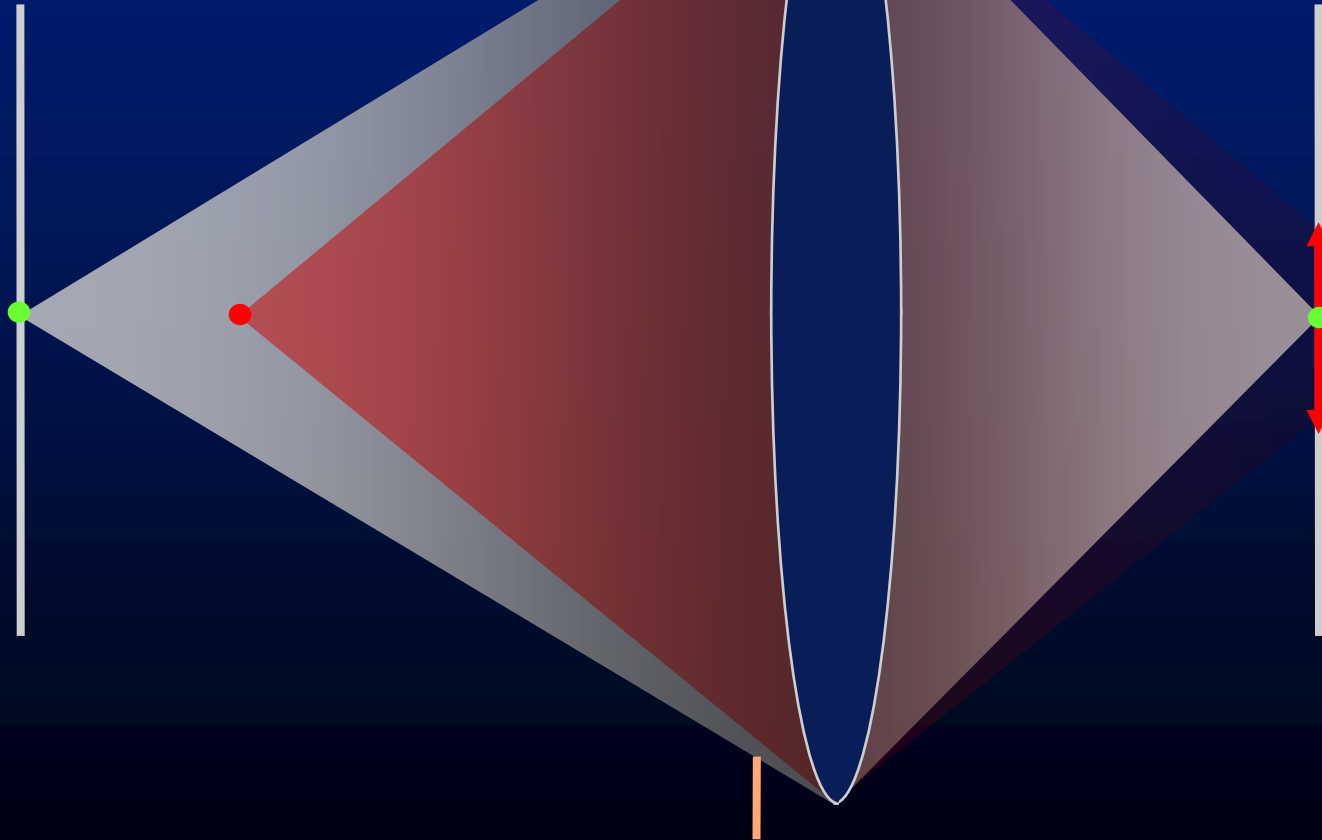
Synthetic aperture photography



Smaller aperture $\rightarrow \rightarrow$ less blur, smaller circle of confusion

Synthetic aperture photography

Merge MANY cameras to act as ONE BIG LENS
Small items are so blurry
they seem to disappear..



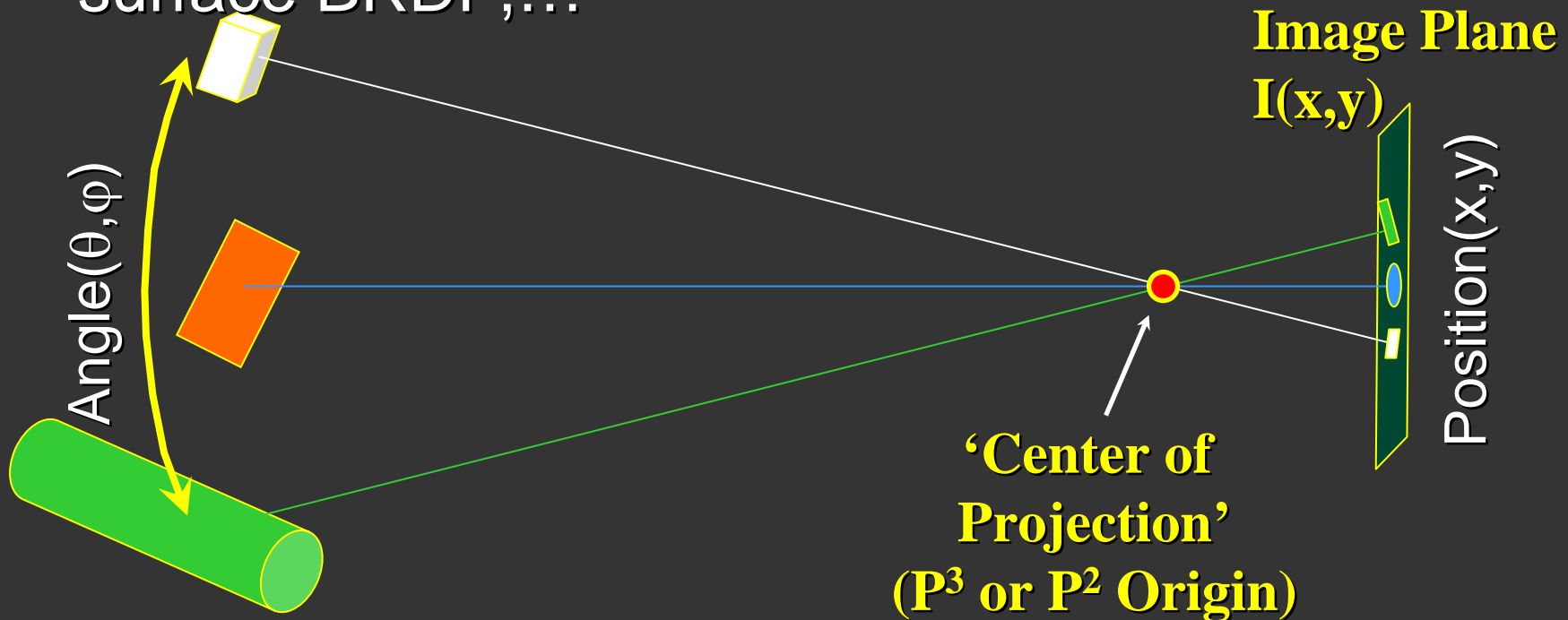
Focus Adjustment: Sum of Bundles



-
- Epsilon Photography
 - Vary focus, exposure polarization, illumination
 - Vary time, view
 - Better than any one photo
 - Achieve effects via multi-photo fusion
 - Create a Super-camera
 - Mimic human eye

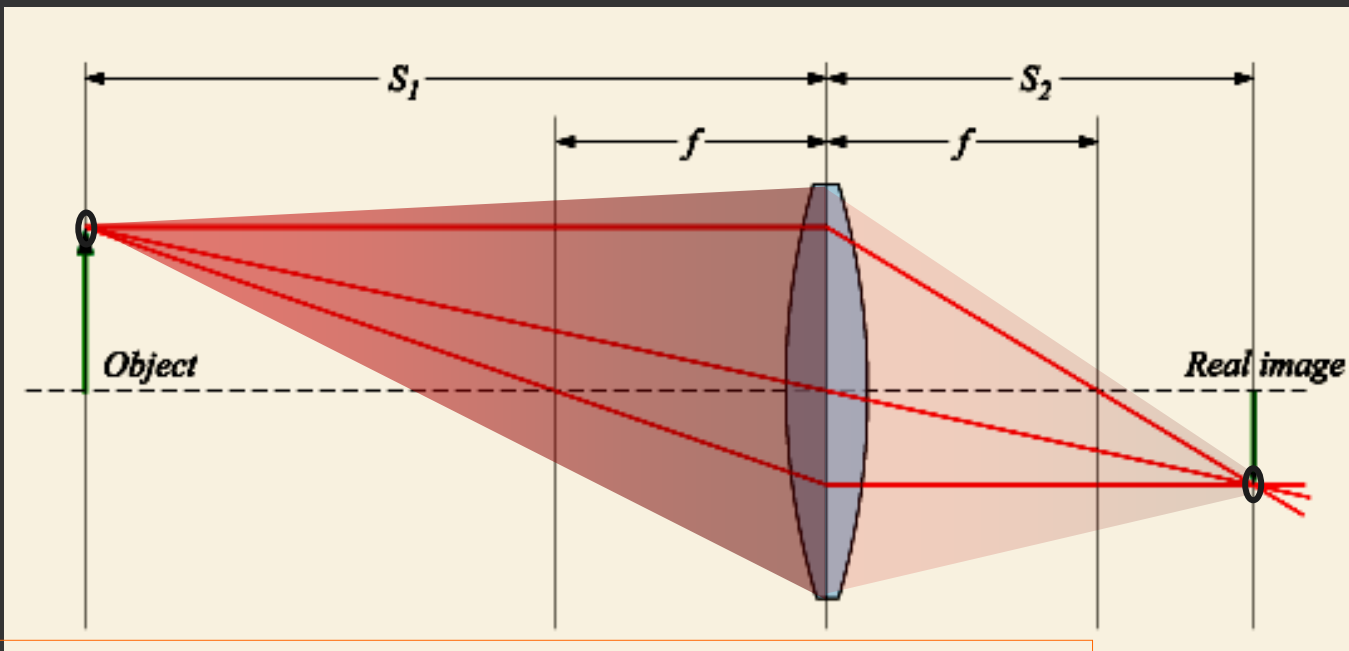
'Film-Like Photography': Ray Model

Light + 3D Scene:  Image:
Illumination,  Planar 2D map of
shape, movement,  light intensities
surface BRDF, ...

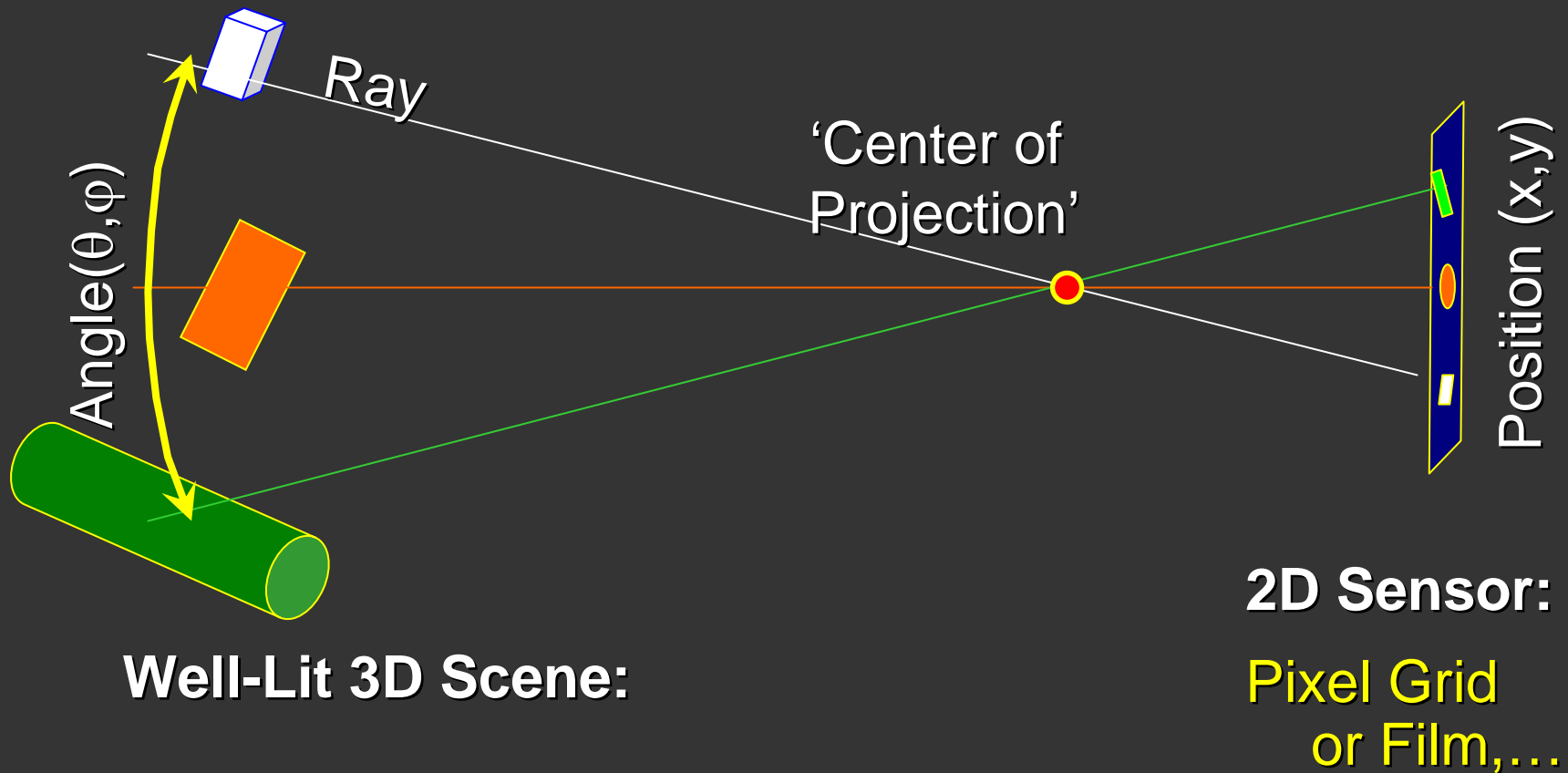


Ray BUNDLES approximate Rays

- Lens Systems:
approximate rays with bundles
- Finite angle, not rays (*lens aperture*)
- Finite area, not points (*circle of confusion*)

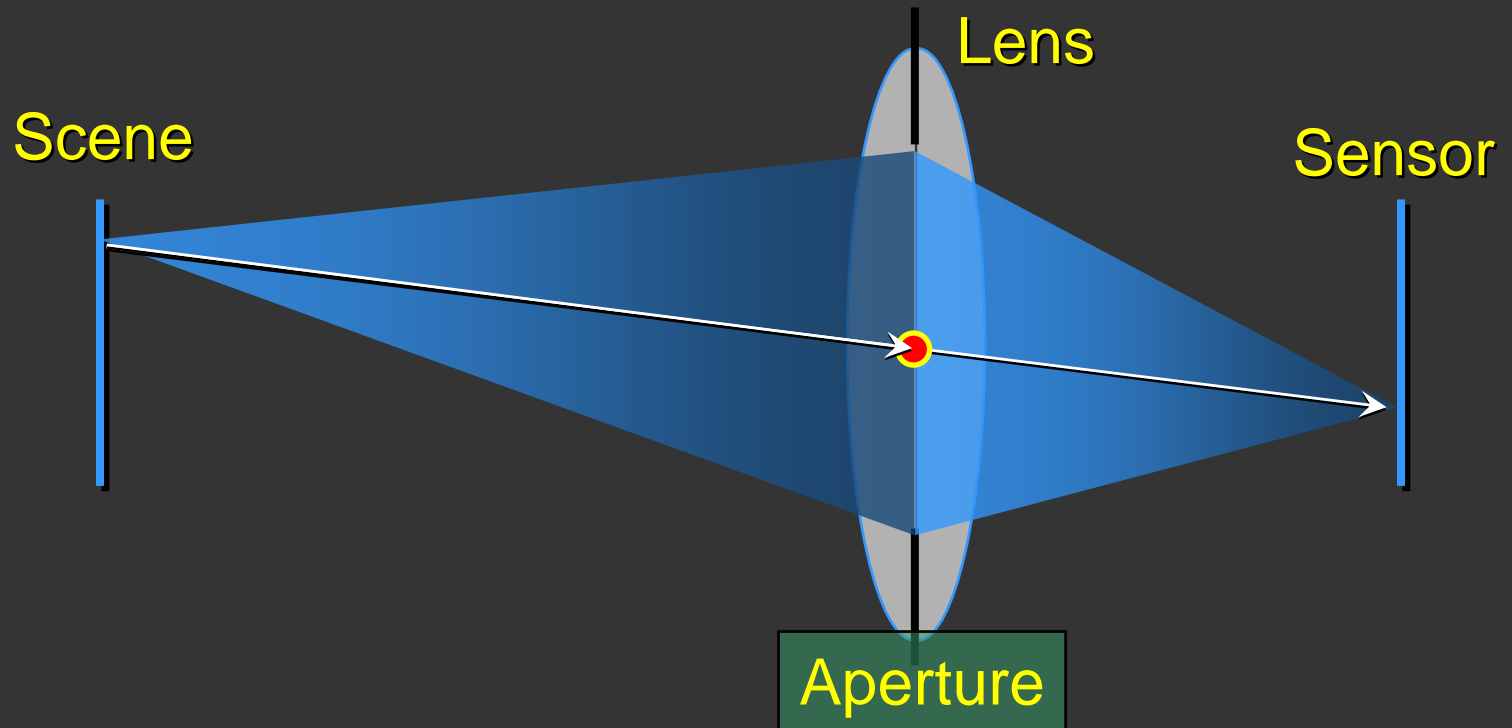


Film-like Optics: Imaging Intuition



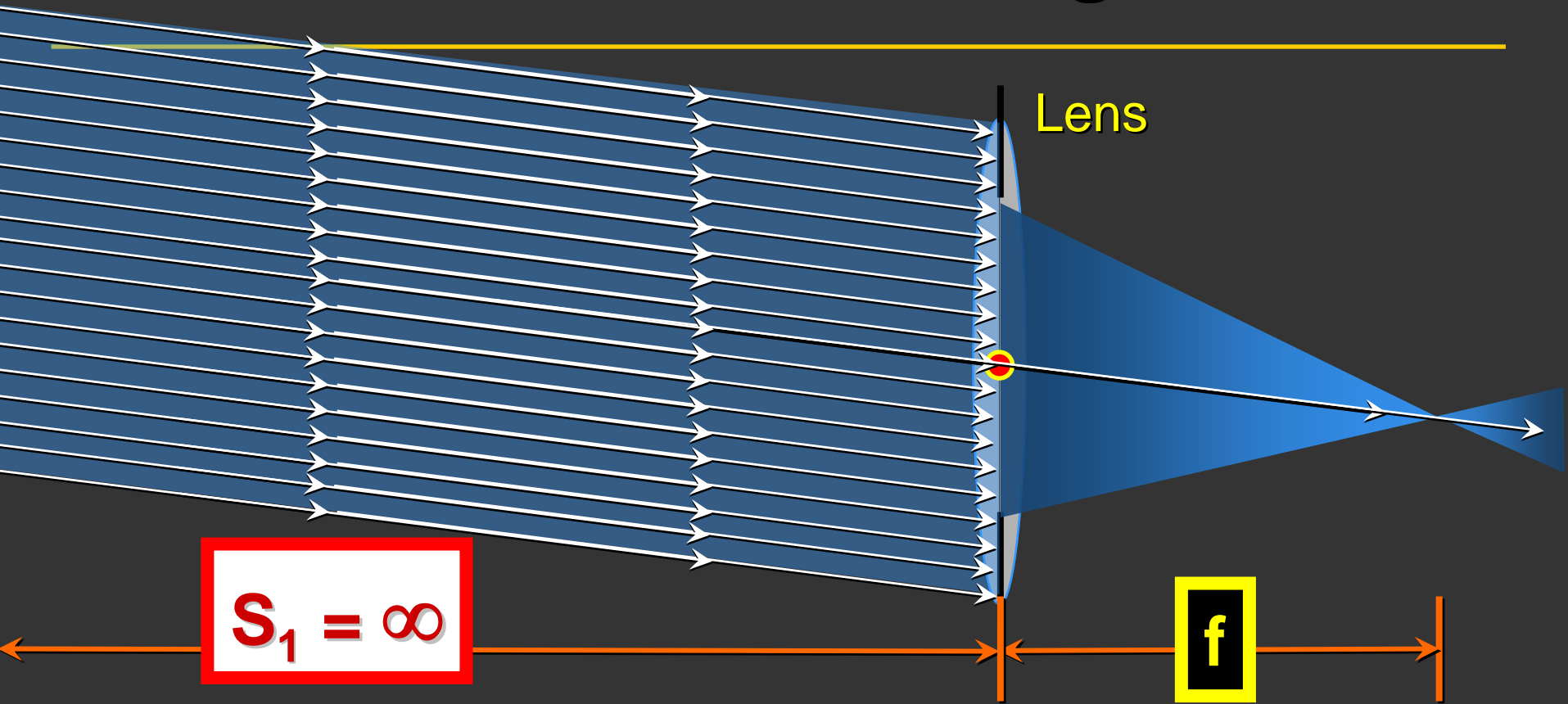
'Pinhole' Model: Rays copy scene onto 'film'

Not *One* Ray, but a *Bundle* of Rays



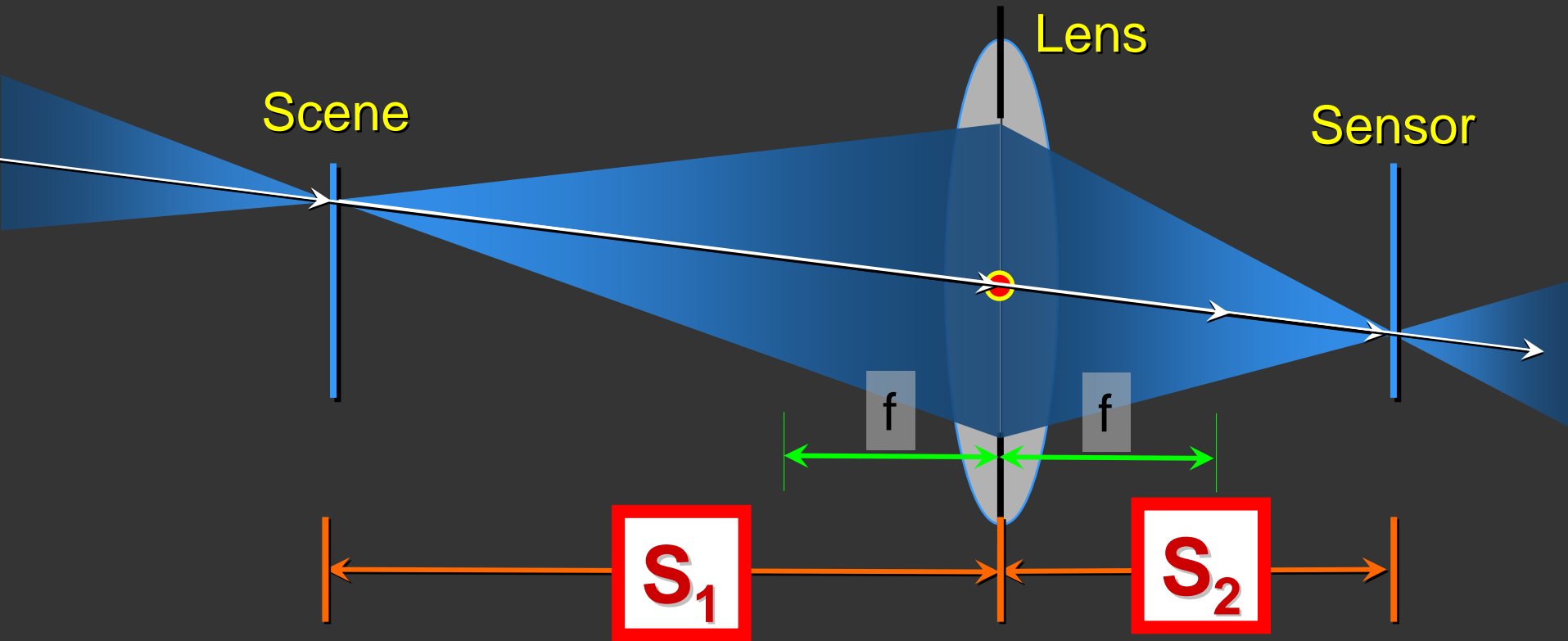
- (BUT Ray model *isn't* perfect: ignores diffraction)
- Lens, aperture, and diffraction sets the point-spread-function (PSF)
(How? See: Goodman, J.W. 'An Introduction to Fourier Optics' 1968)

Review: Focal Length f



- Lens focal length f : where parallel rays converge
- greater focal length: less ray-bending ability...
- For flat glass; for air : $f = \infty$

Review: Thin Lens Law



• **Thin Lens Law:** in focus when:

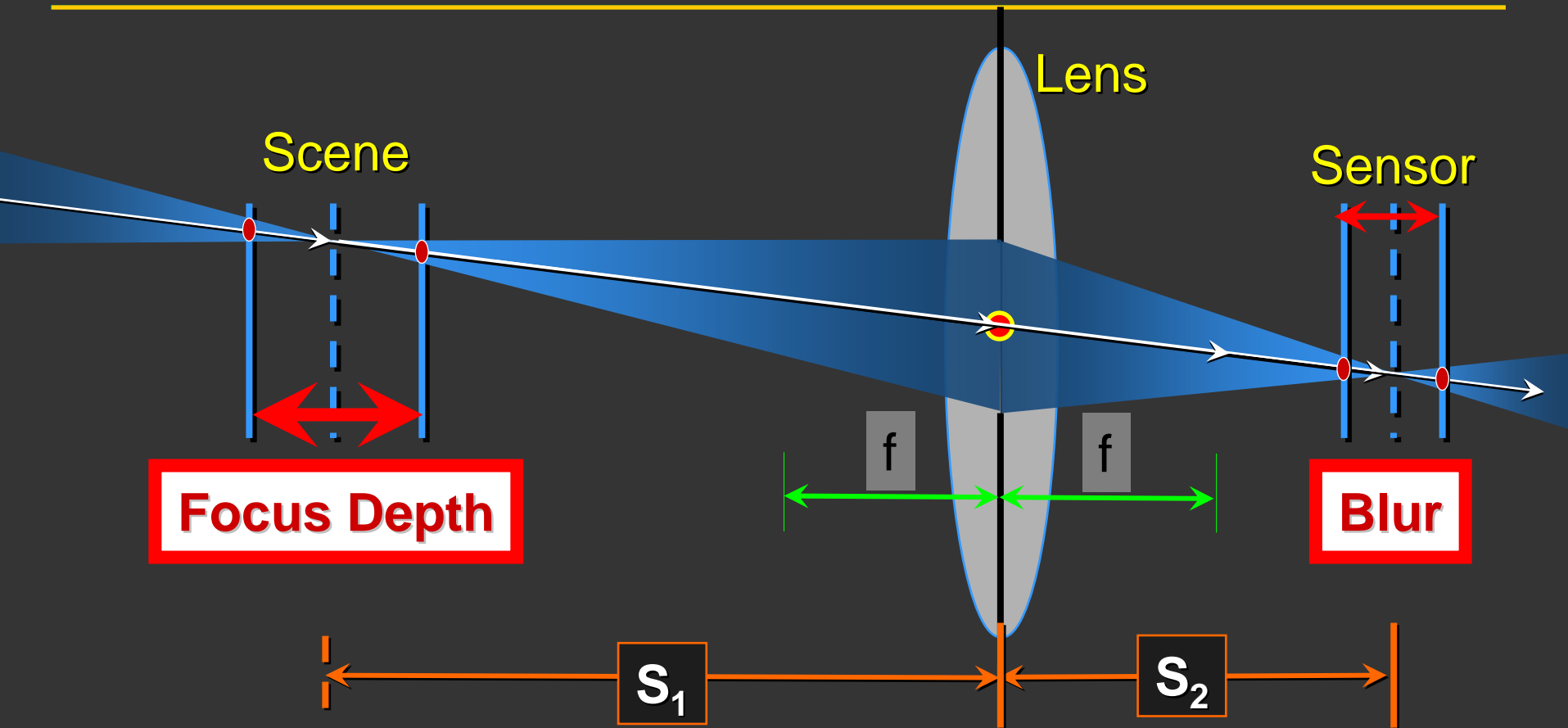
• Note that $S_1 \geq f$ and $S_2 \geq f$

$$\frac{1}{S_1} + \frac{1}{S_2} = \frac{1}{f}$$

Try it Live! Physlets...

<http://webphysics.davidson.edu/Applets/Optics/intro.html>

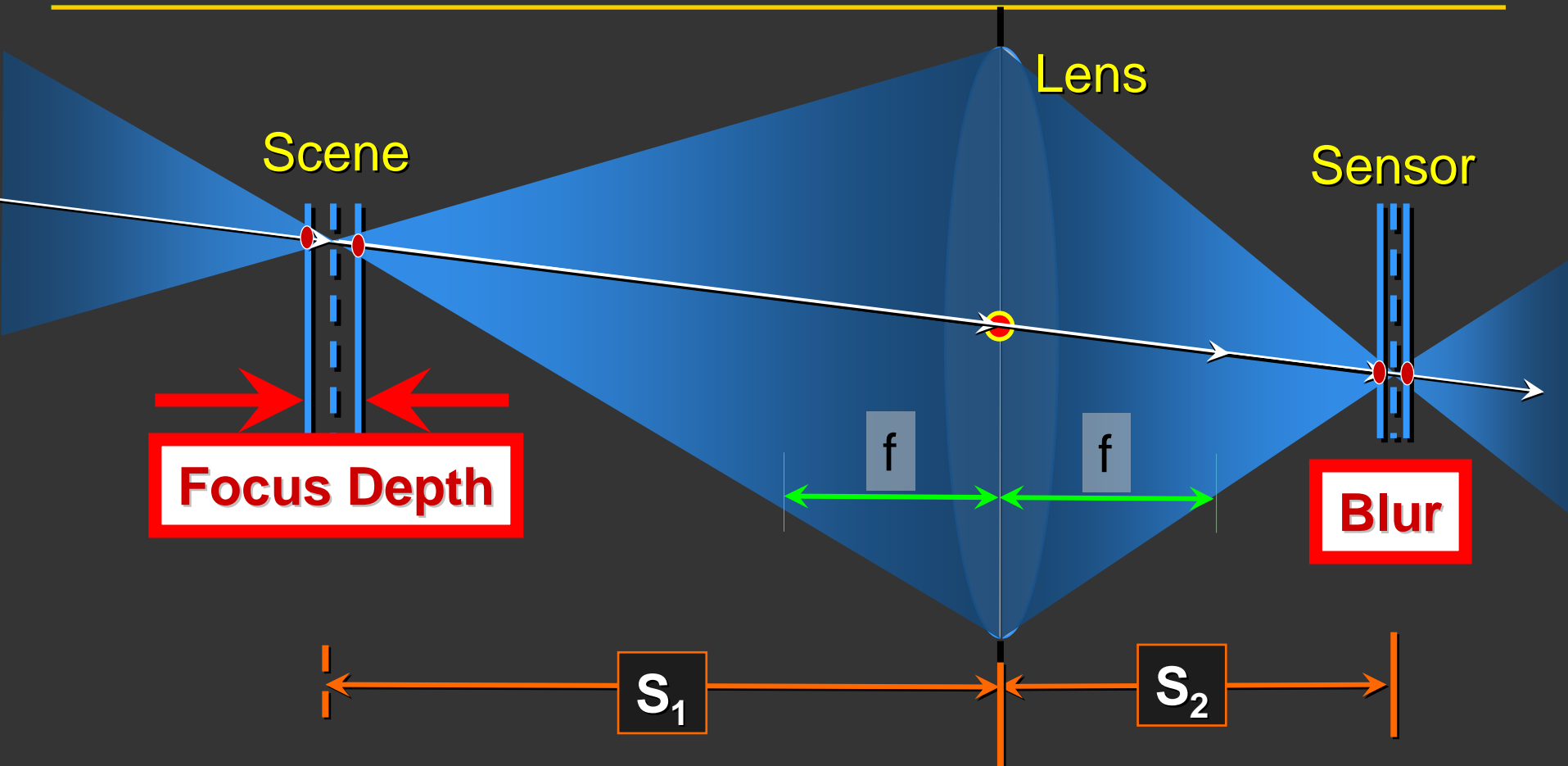
Aperture and Depth-Of-Focus:



For same focal length:

- Smaller **Aperture** → Larger focus depth, but less light

Aperture and Depth-Of-Focus:



For same focal length:

- Larger **Aperture** → smaller focus depth, but more light

Focal Length vs. Viewpoint vs. Focus

Wide angle



Standard



Telephoto



Large/Deep



← Depth of Focus

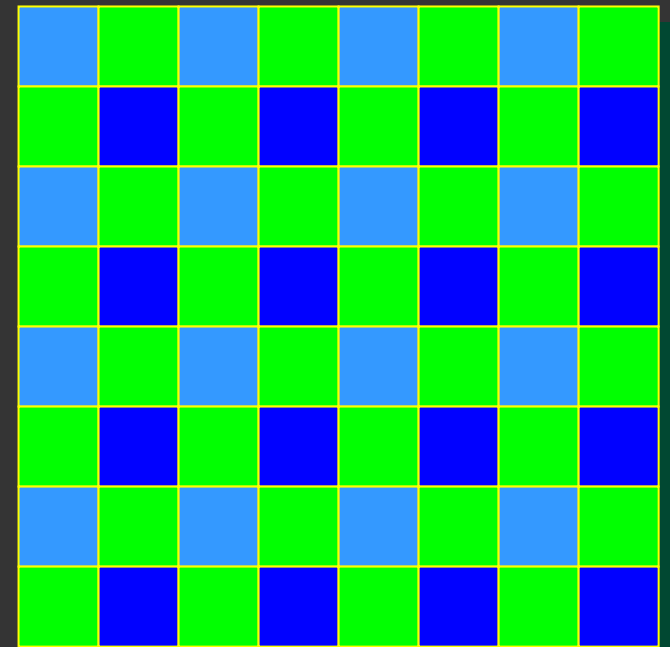
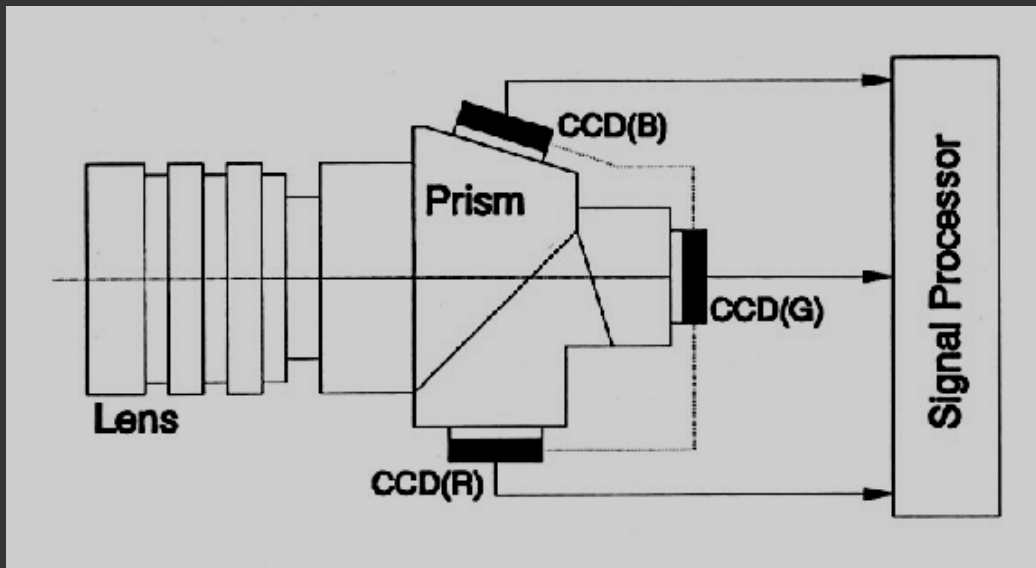


Small/shallow

Wide angle isn't flattering; do you know why?

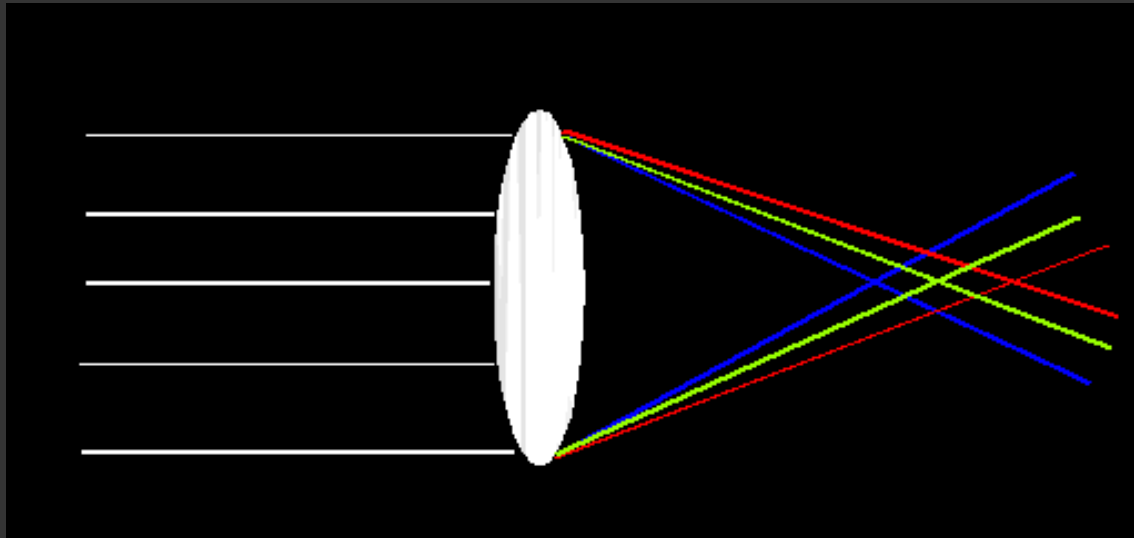
Color Sensing

- 3-chip: separate R,G,B sensors, vs.
- 1-chip: interleaved R,G,B: quality vs. cost



Lens Flaws: Chromatic Aberration

- **Dispersion:** wavelength-dependent refractive index
 - (enables prism to spread white light beam into rainbow)
- Modifies ray-bending and lens focal length: $f(\lambda)$



- color fringes near edges of image
- Correction: a so-called 'doublet' lens of flint glass, etc.
<http://www.swgc.mun.ca/physics/physlets/opticalbench.html>

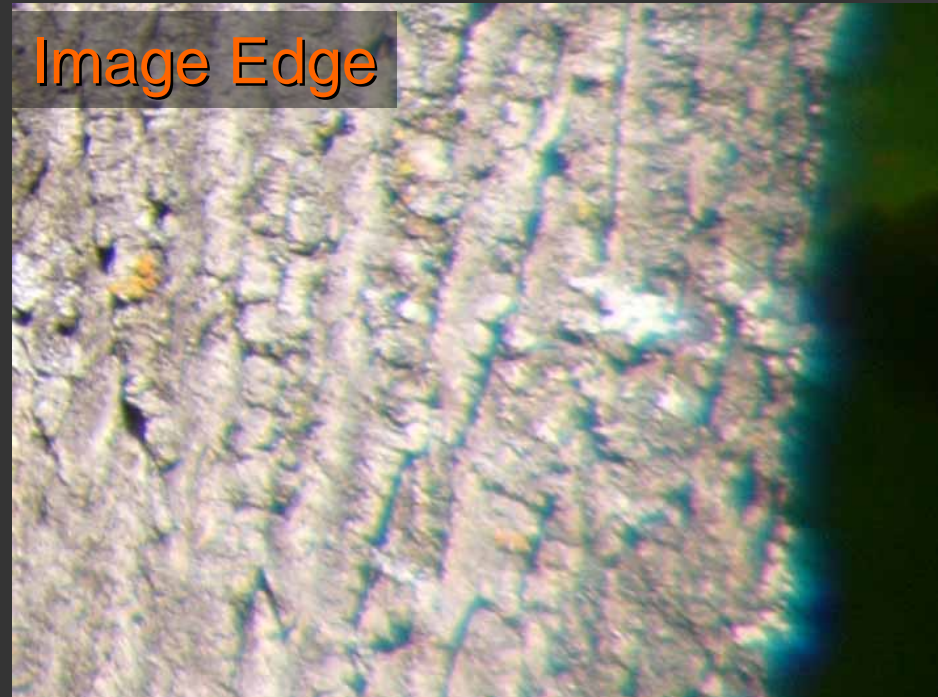
Chromatic Aberration

- **Lens Design Fix:** Multi-element lenses
Complex, expensive, many tradeoffs!
- **Computed Fix:** Geometric warp for R,G,B

Image Center



Image Edge



Many Limitations & Tradeoffs:

(how can computing change them?)

- Optics:

 - Single focus distance, limited depth-of-field, limited field-of-view, internal reflections/flare/glare

- Lighting:

 - Camera has no knowledge of ray source strength, position, direction; little control (e.g. flash)

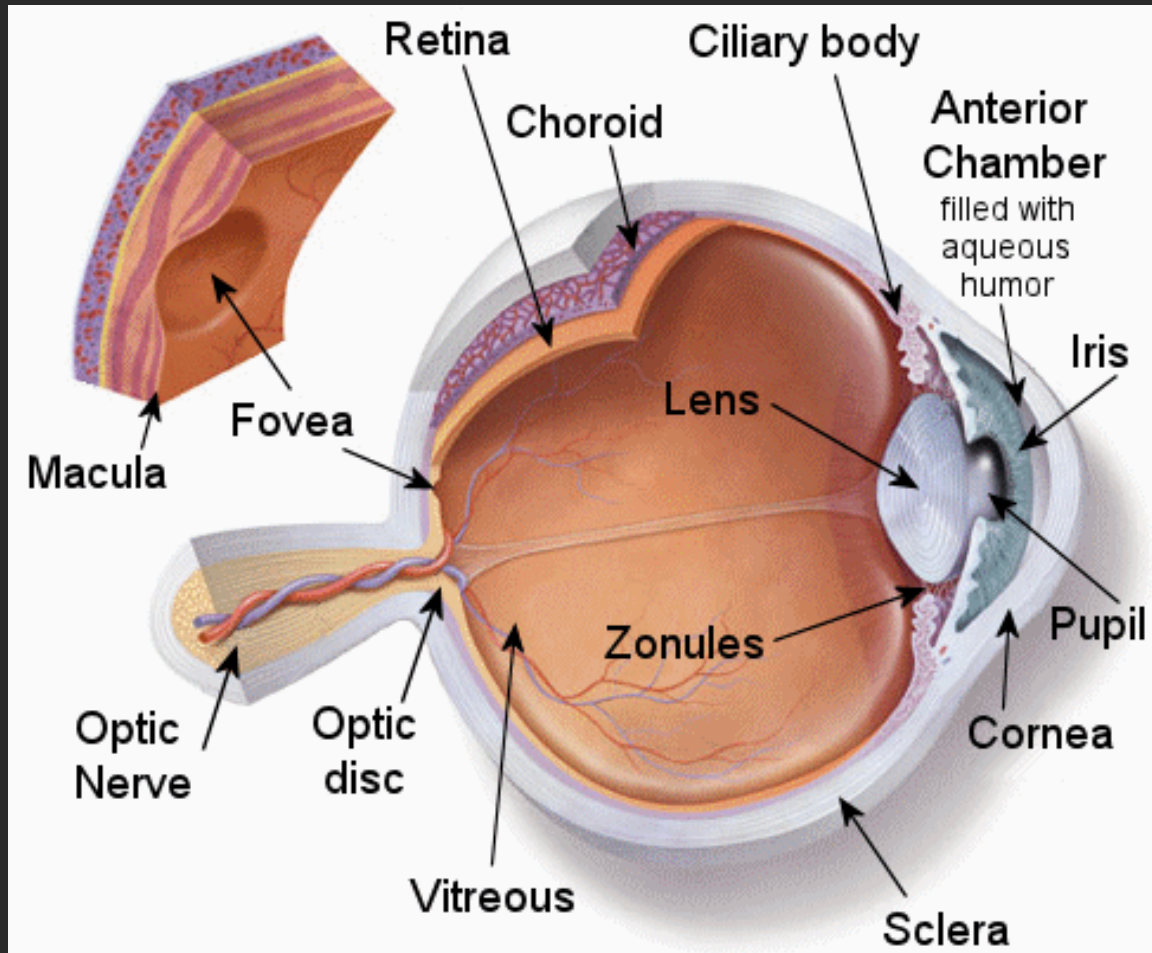
- Sensor:

 - Exposure setting, motion blur, noise, response time,...

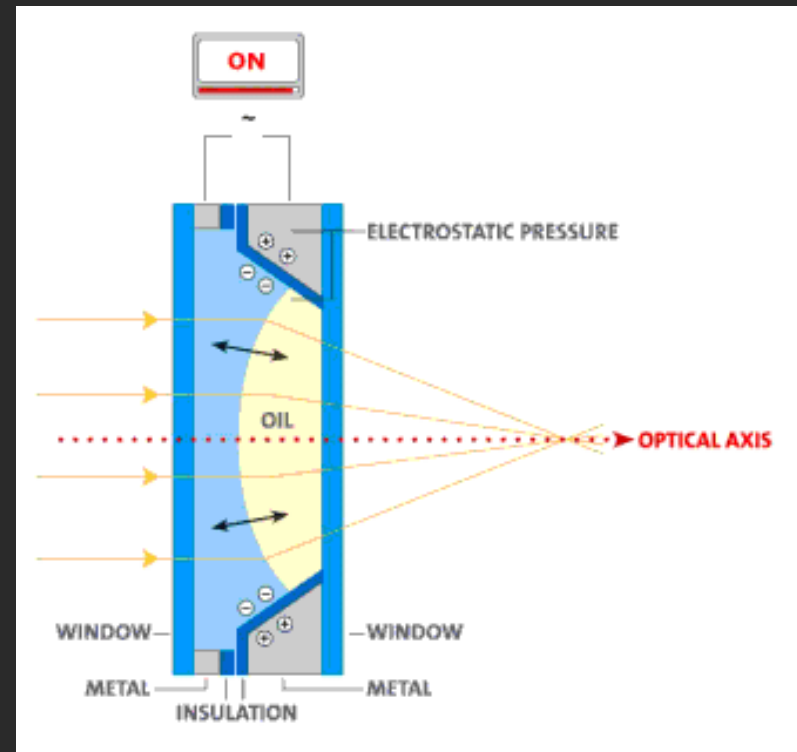
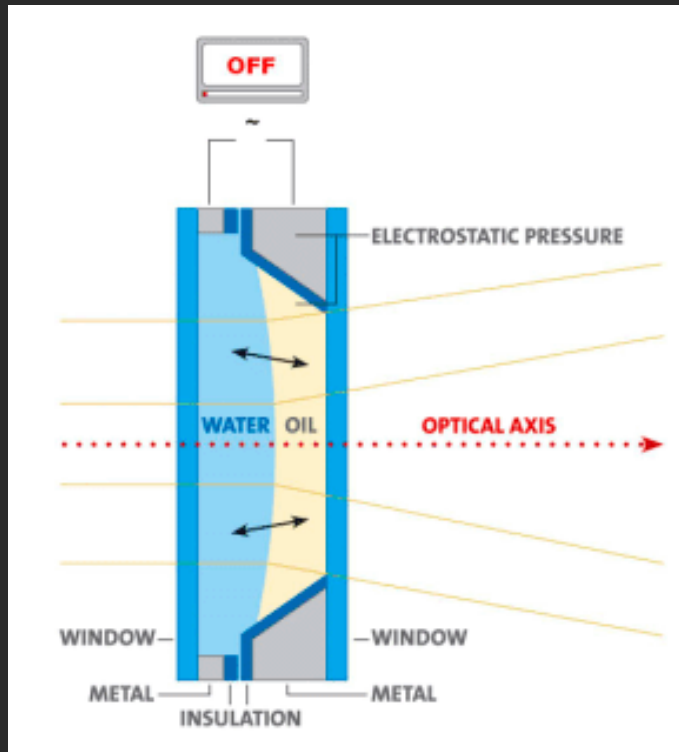
- Processing:

 - Quantization/color depth, camera shake, scene movement...

The Eye's Lens



Varioptic Liquid Lens: Electrowetting



Varioptic, Inc., 2007

Varioptic Liquid Lens



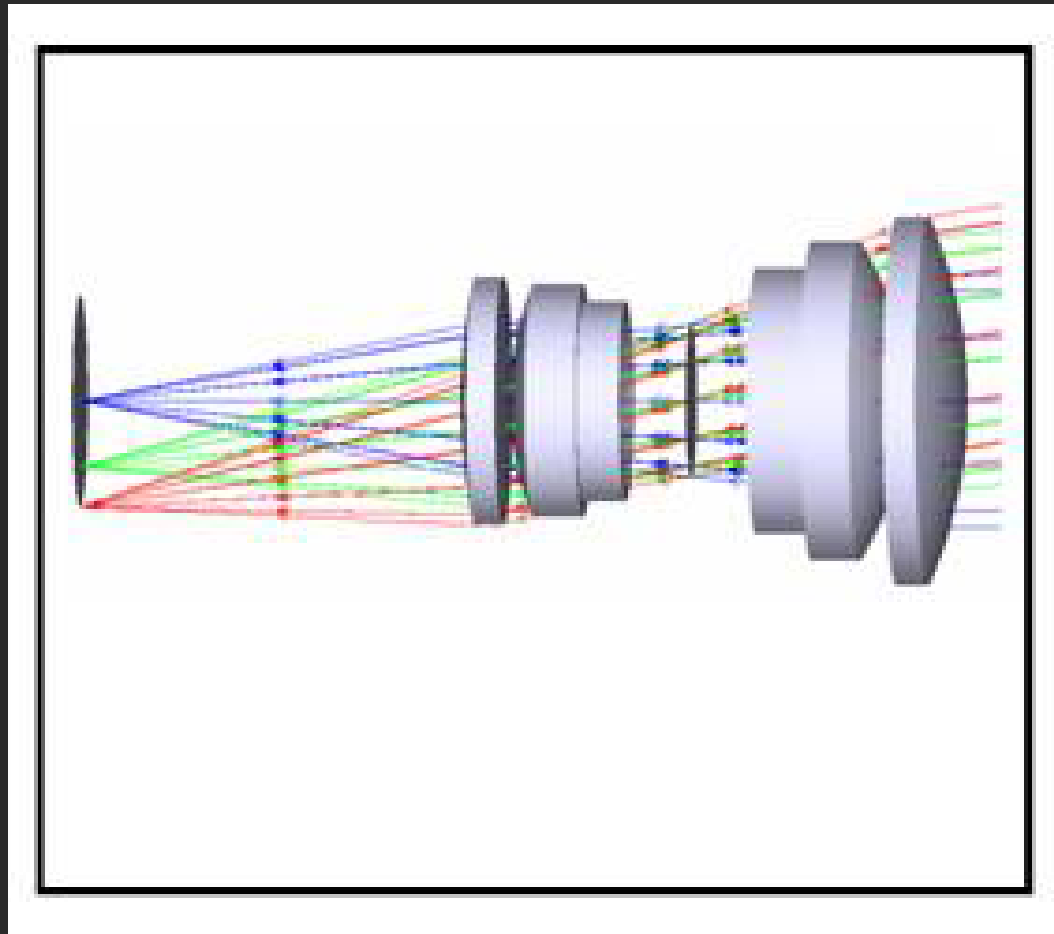
(Courtesy Varioptic Inc.)

Captured Video

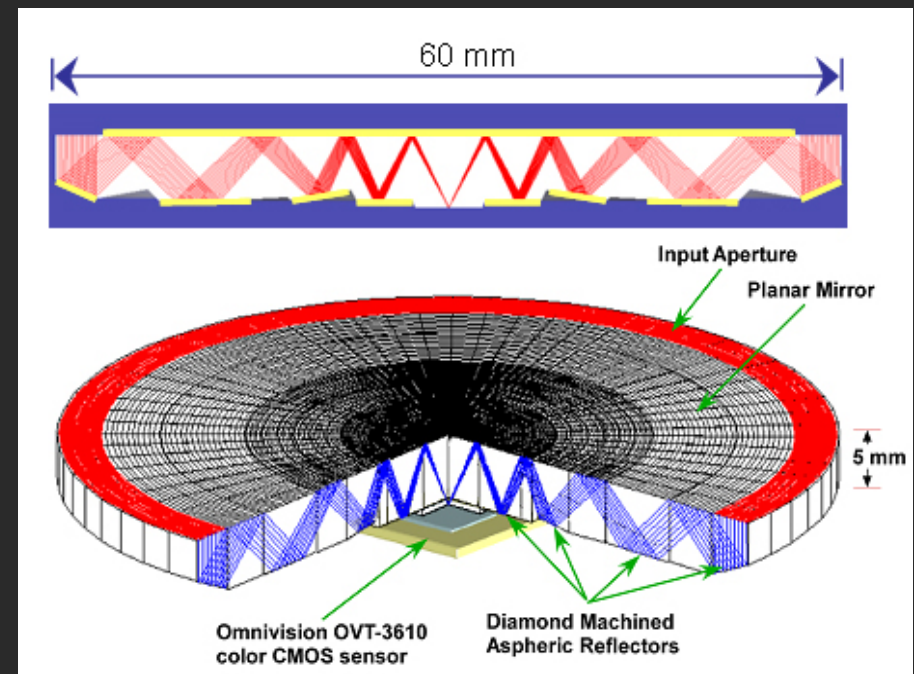
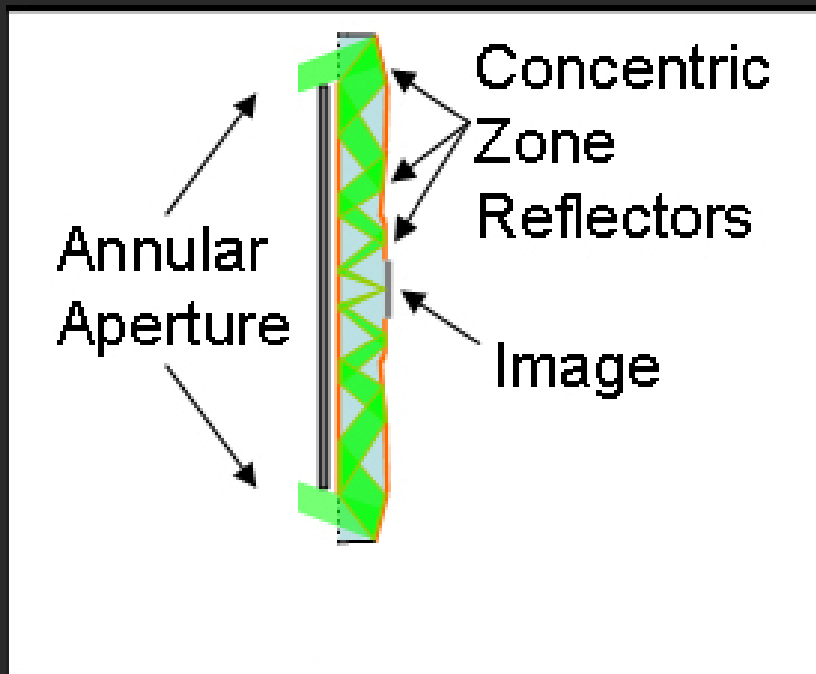


(Courtesy Varioptic Inc.)

Conventional Compound Lens

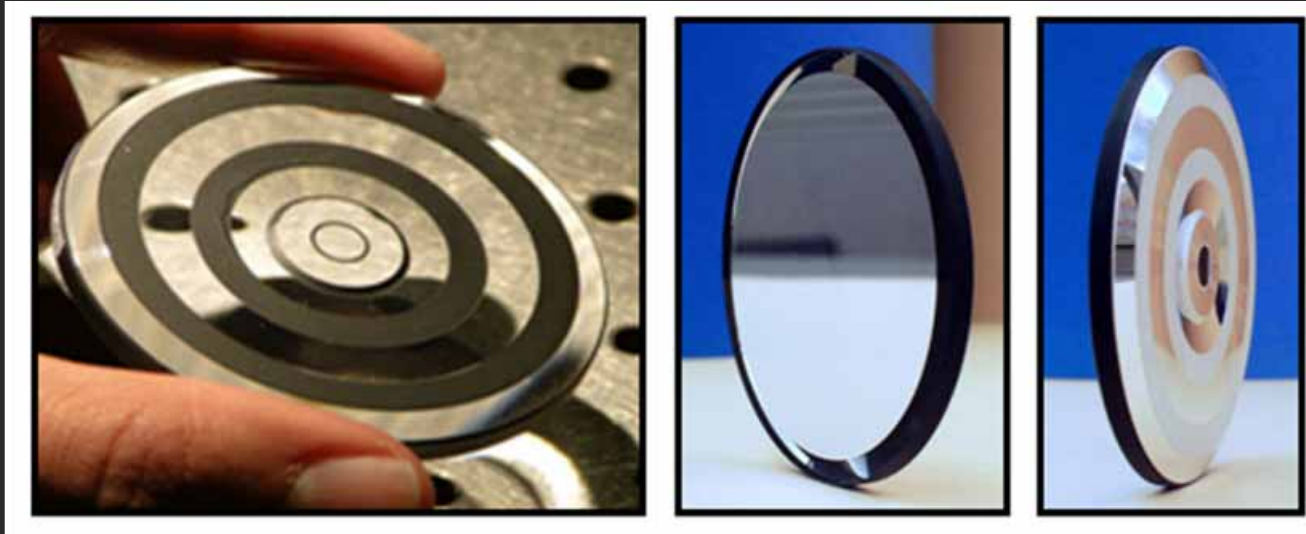


“Origami Lens”: Thin Folded Optics (2007)



“Ultrathin Cameras Using Annular Folded Optics,”
E. J. Tremblay, R. A. Stack, R. L. Morrison, J. E. Ford
Applied Optics, 2007 - OSA

Origami Lens



Conventional
Lens

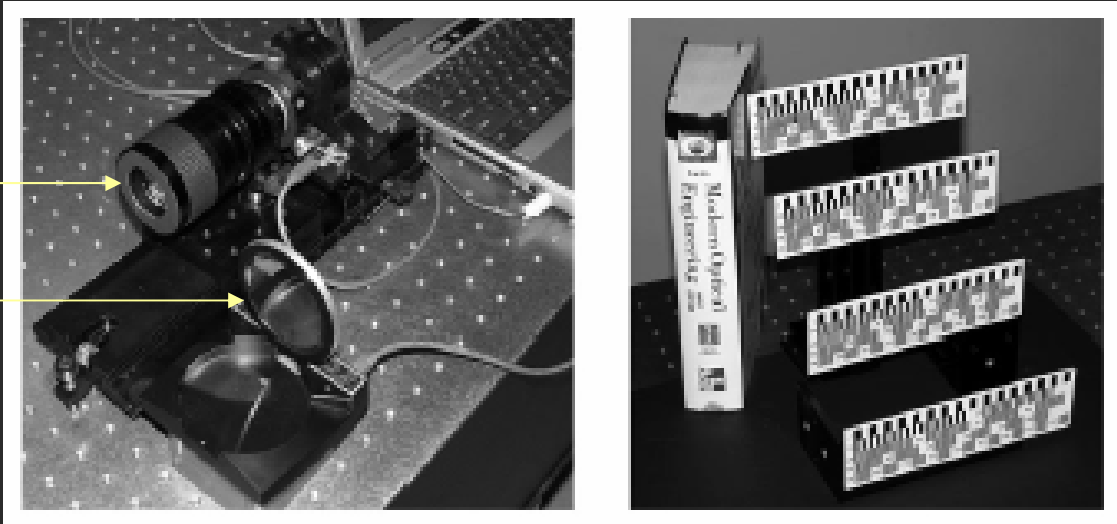


Origami
Lens

Optical Performance

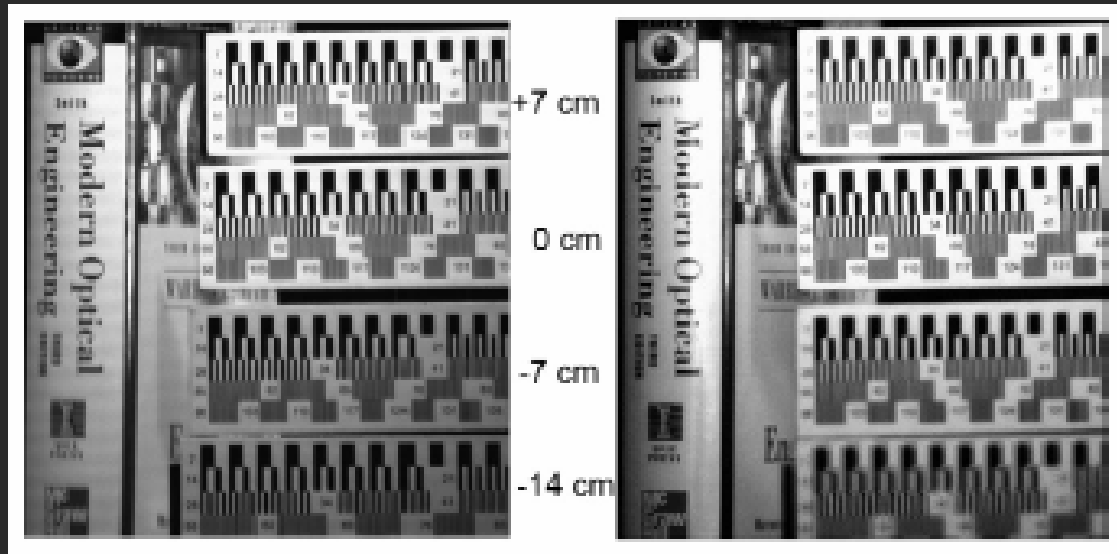
Conventional

Origami



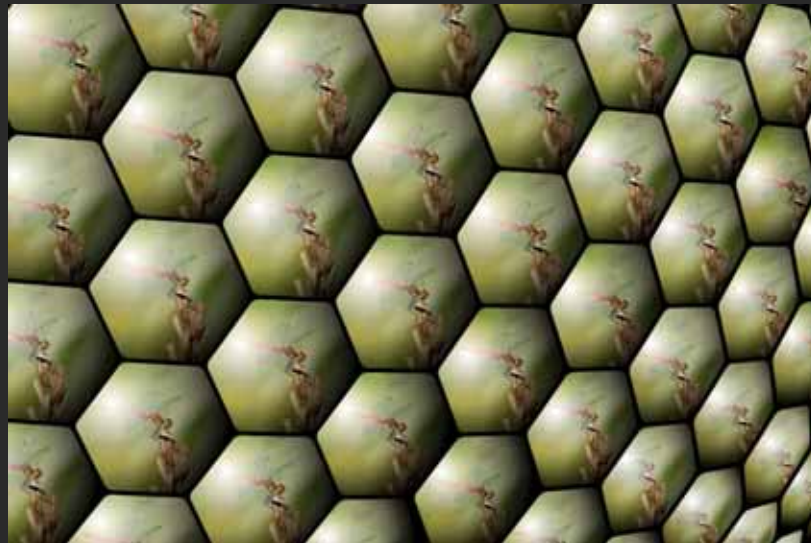
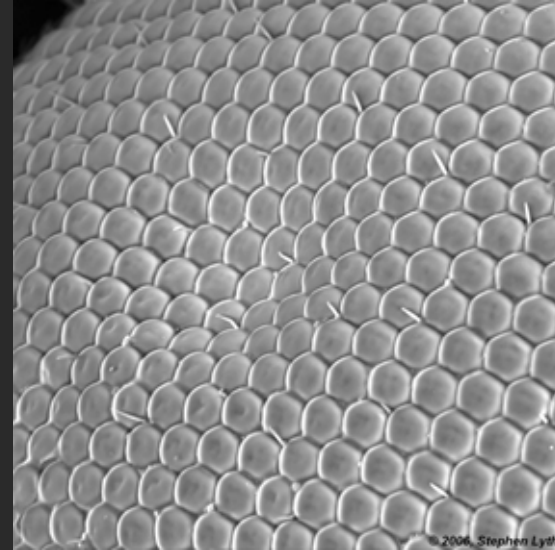
Scene

Conventional
Lens Image

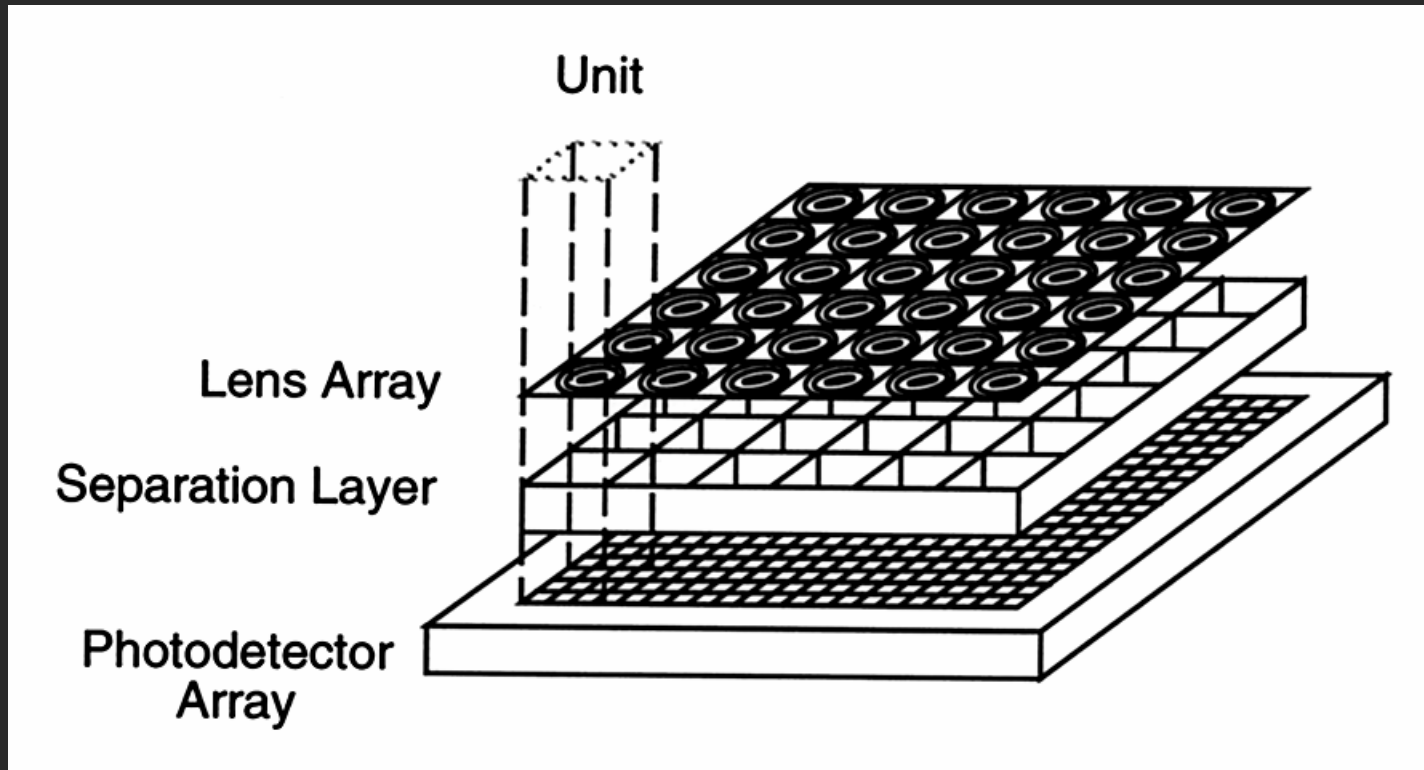


Origami
Lens Image

Compound Lens of Dragonfly

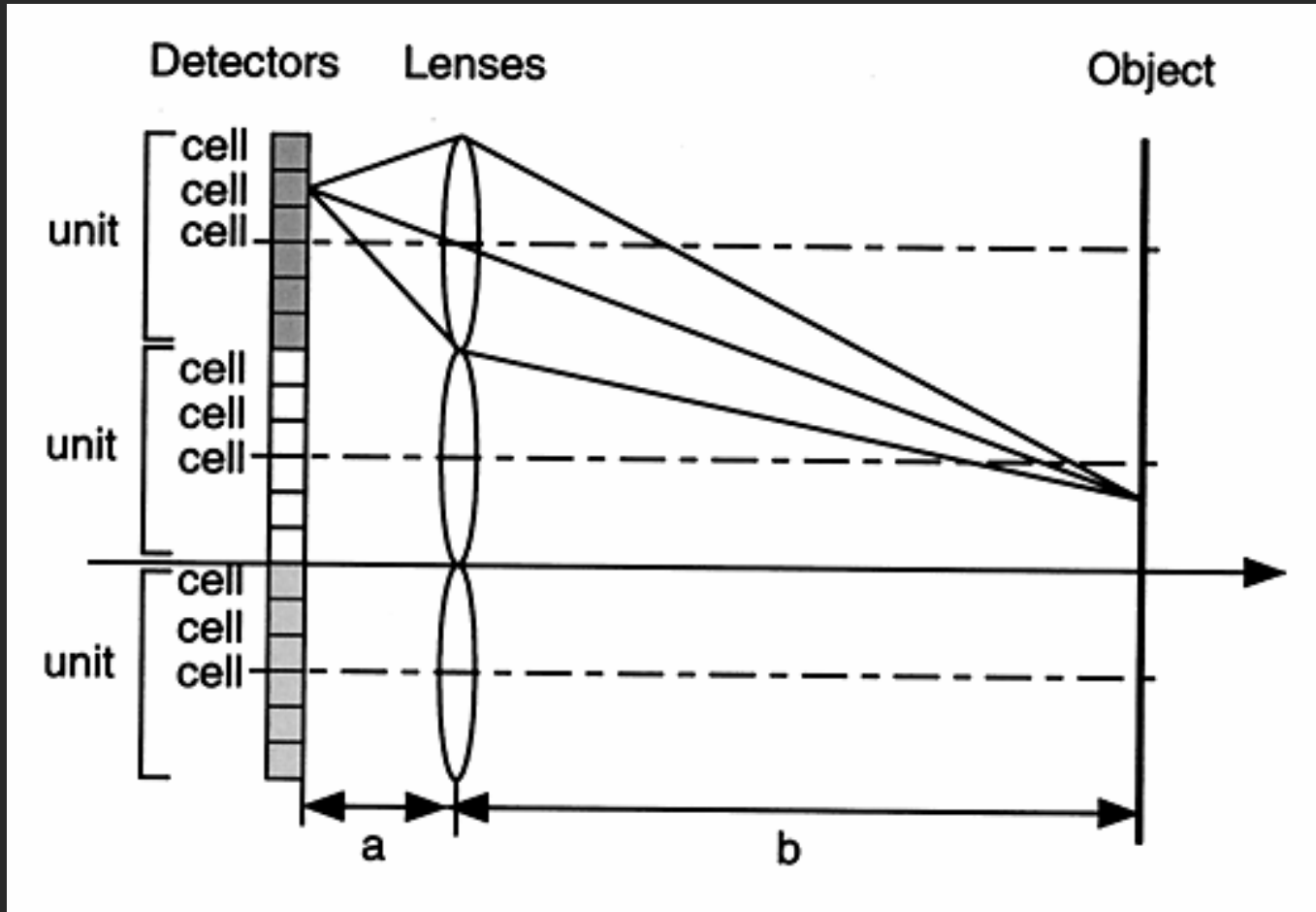


TOMBO: Thin Camera (2001)



"Thin observation module by bound optics (TOMBO),"
J. Tanida, T. Kumagai, K. Yamada, S. Miyatake
Applied Optics, 2001

TOMBO: Thin Camera



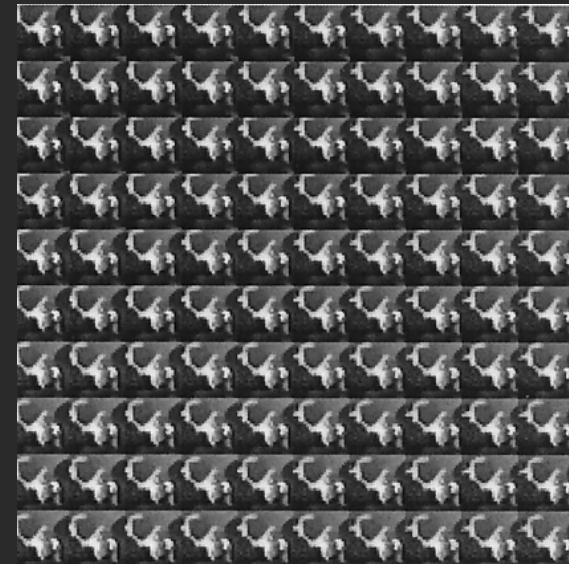
Captured Image



Scene



T
O
M
B
O



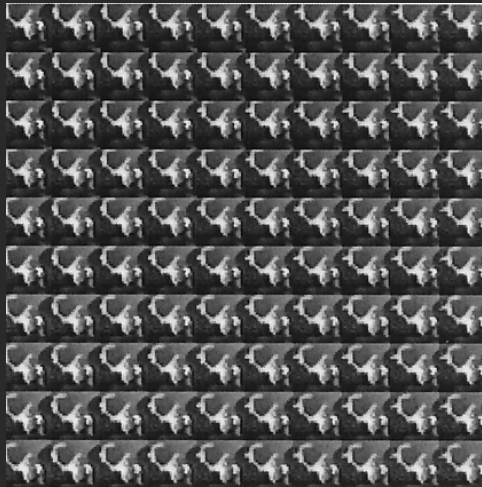
Captured Image

(Multiple low-resolution
copies of the scene)

$$\mathbf{g} = \mathbf{Hf}$$

Image = Optics . Scene

Reconstructed Image



$$\mathbf{f} = \mathbf{H}^+ \mathbf{g}$$



Conventional Lens: Limited Depth of Field

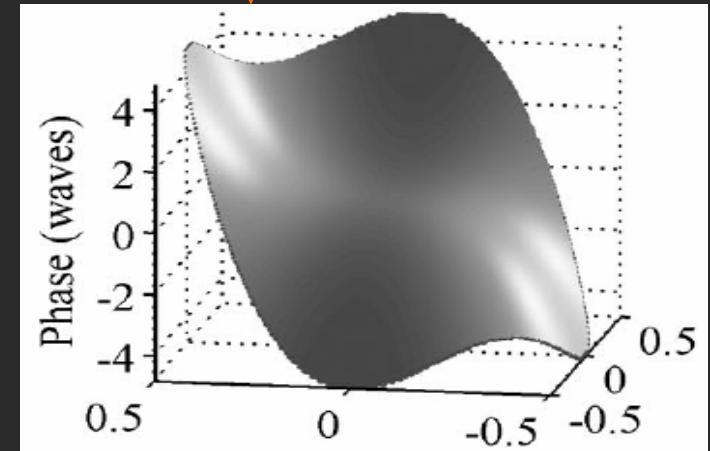
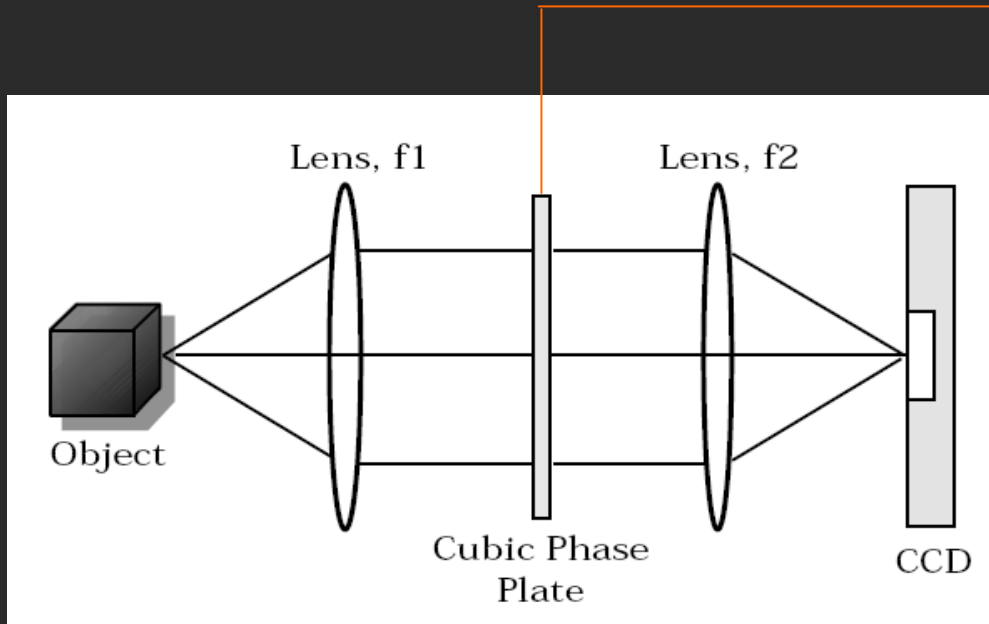
Open
Aperture



Smaller
Aperture



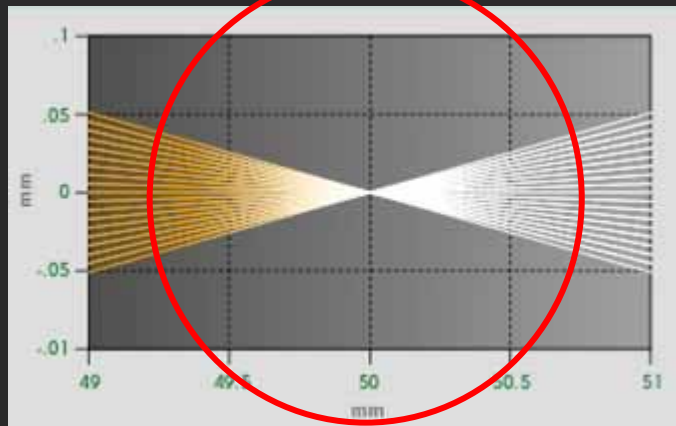
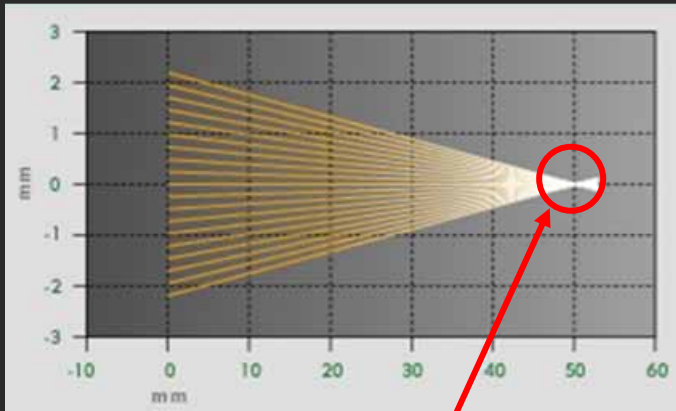
Wavefront Coding using Cubic Phase Plate



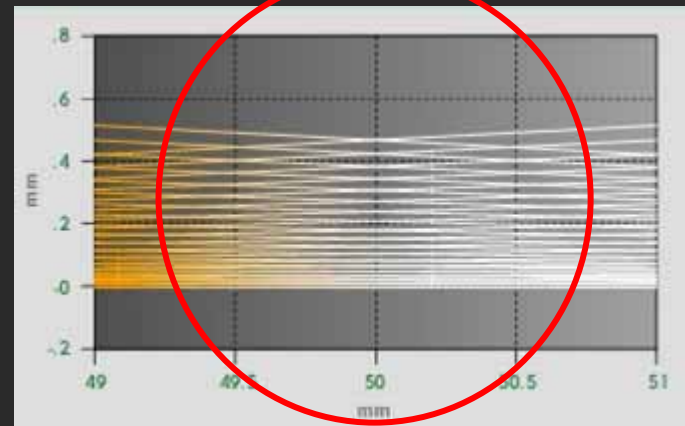
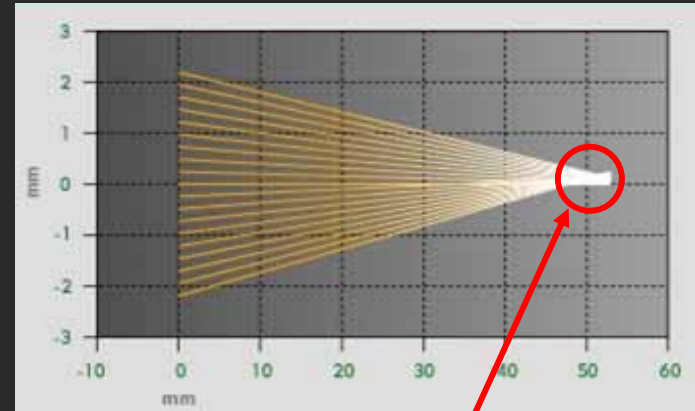
*"Wavefront Coding: jointly optimized optical and digital imaging systems",
E. Dowski, R. H. Cormack and S. D. Sarama ,
Aerosense Conference, April 25, 2000*

Depth Invariant Blur

Conventional System



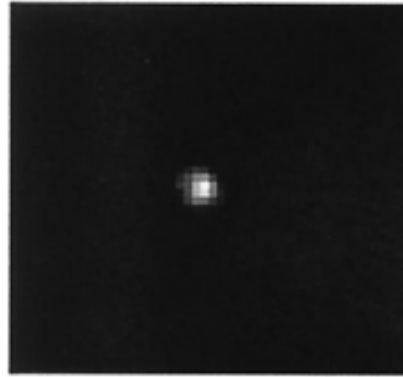
Wavefront Coded System



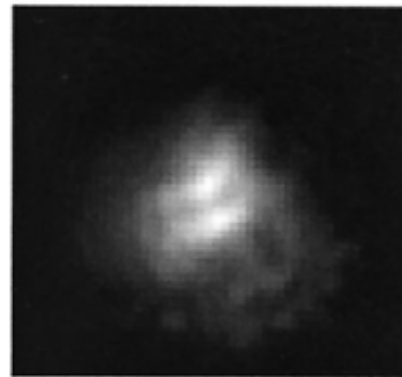
Point Spread Functions

Focused

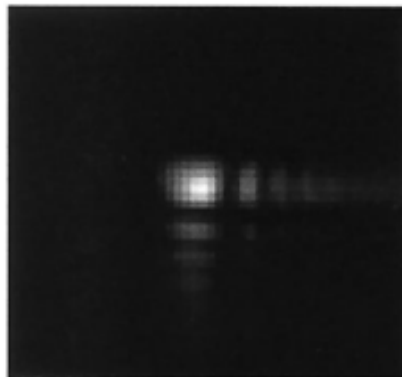
Defocused



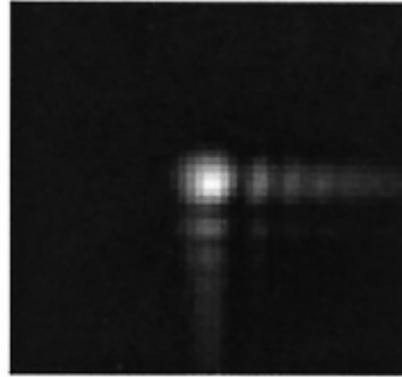
(A)



(B)



(C)



(D)

Conventional

Wavefront Coded

Example

Conventional System

Open Aperture



Stopped Down



Wavefront Coded System

Captured Image



After Processing



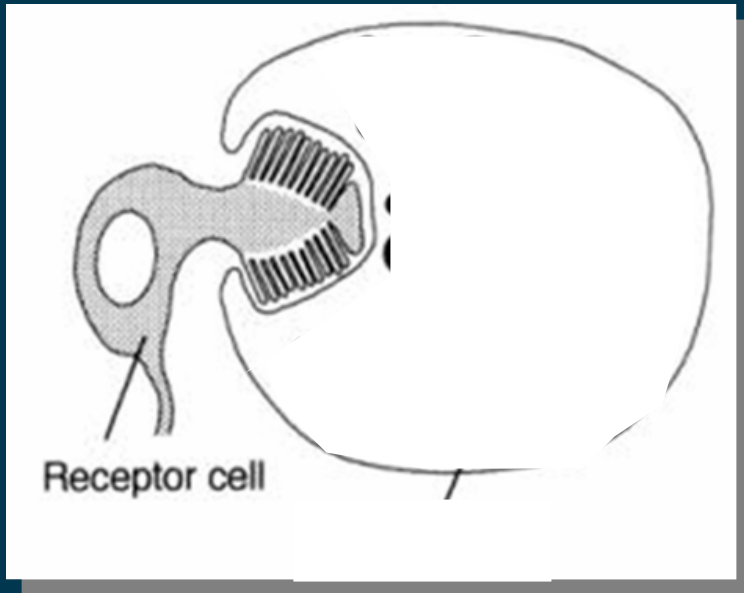
Wavelength Manipulation

- Sunglasses changing color instantly
- Electrochromic Polymer sensitive to current levels



Chunye Xu, University of Washington

Simplest Visual Organs

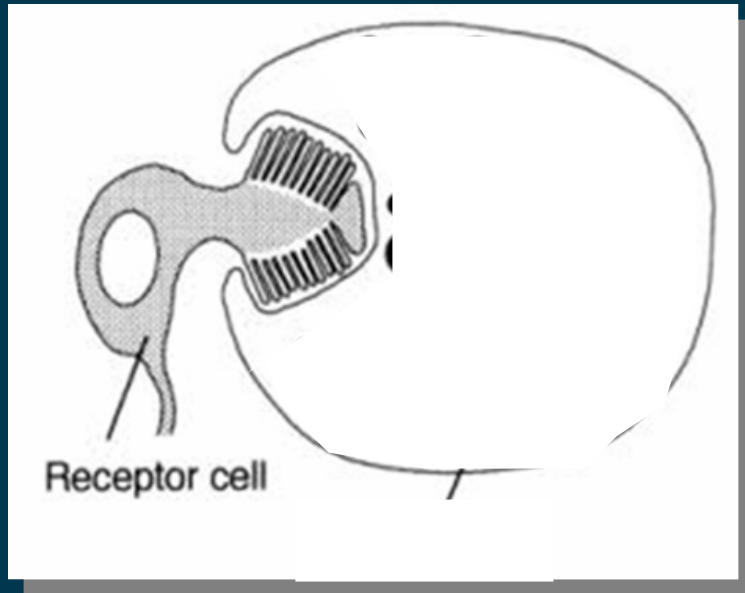


Larval Trematode Worm

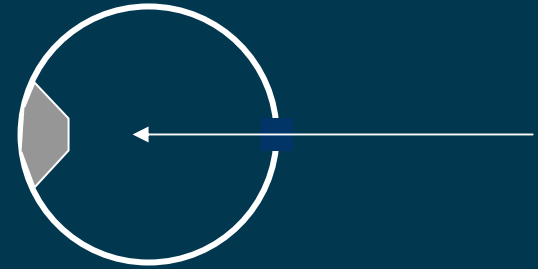


'Single Pixel' Camera

Simplest Visual Organs

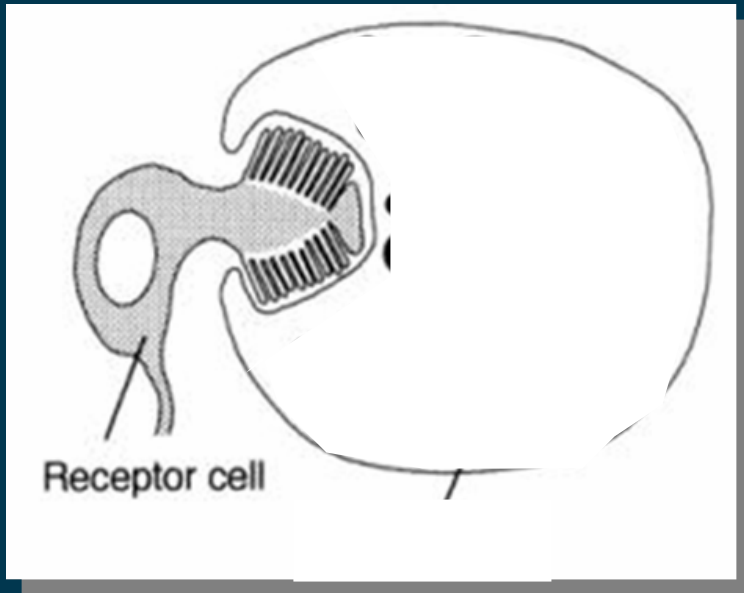


Larval Trematode Worm

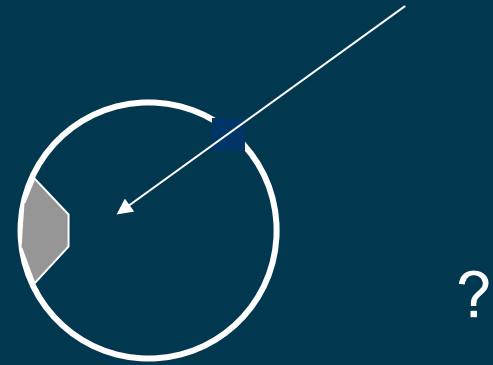


'Single Pixel' Camera

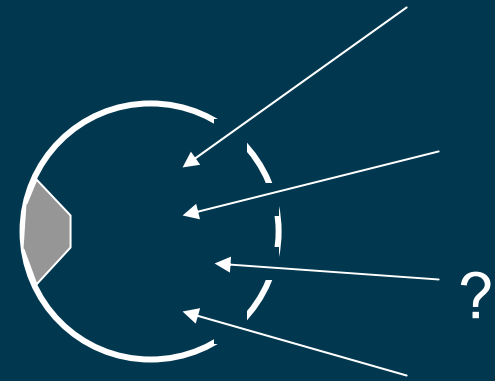
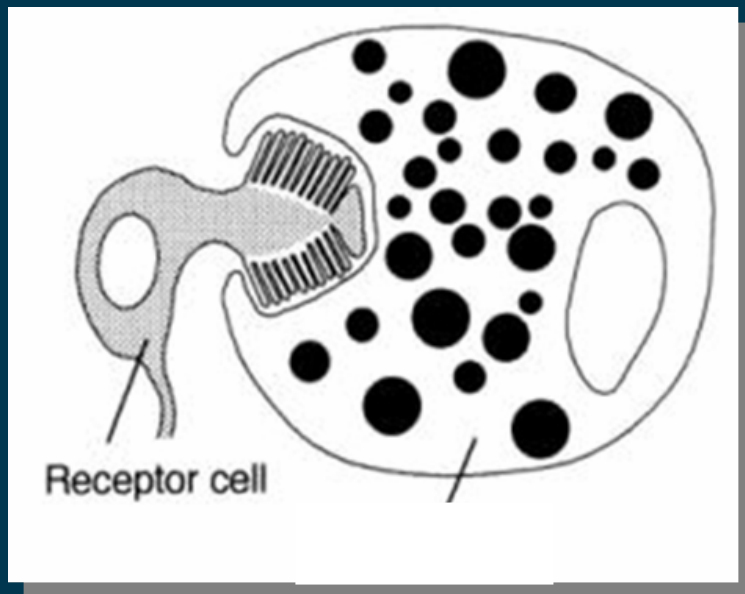
Simplest Visual Organs



Larval Trematode Worm



Special Aperture



Larval Trematode Worm

Special Aperture

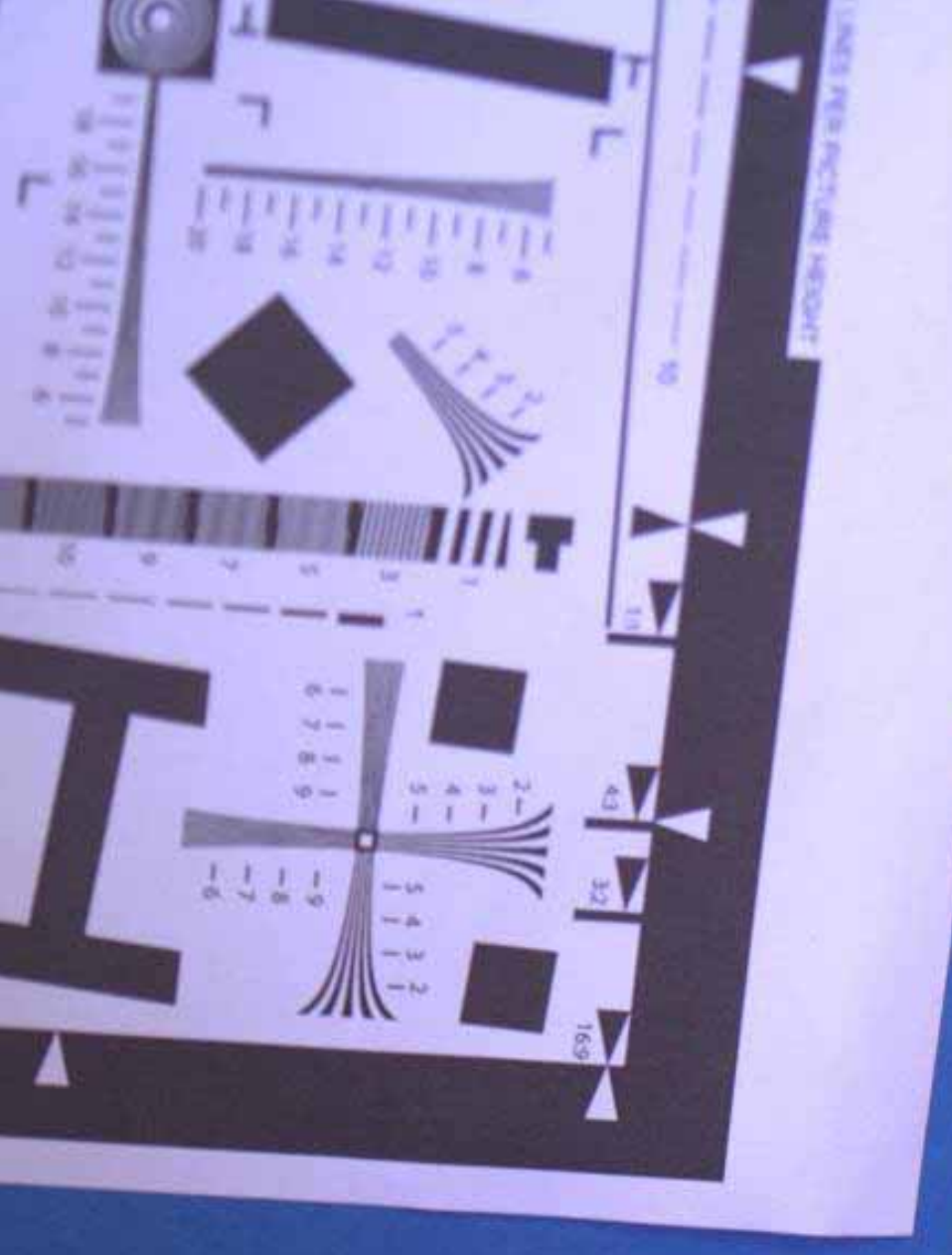


The aperture of a 100 mm lens is modified



Insert a **coded mask** with chosen binary pattern

Rest of the camera is unmodified



LED

In Focus Photo

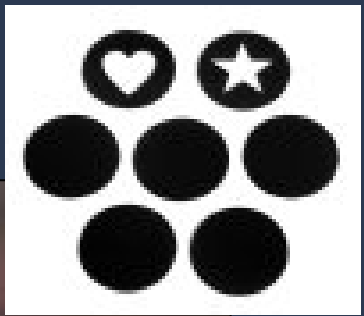


Out of Focus Photo: Open Aperture



Out of Focus Photo: Coded Aperture

Bokeh







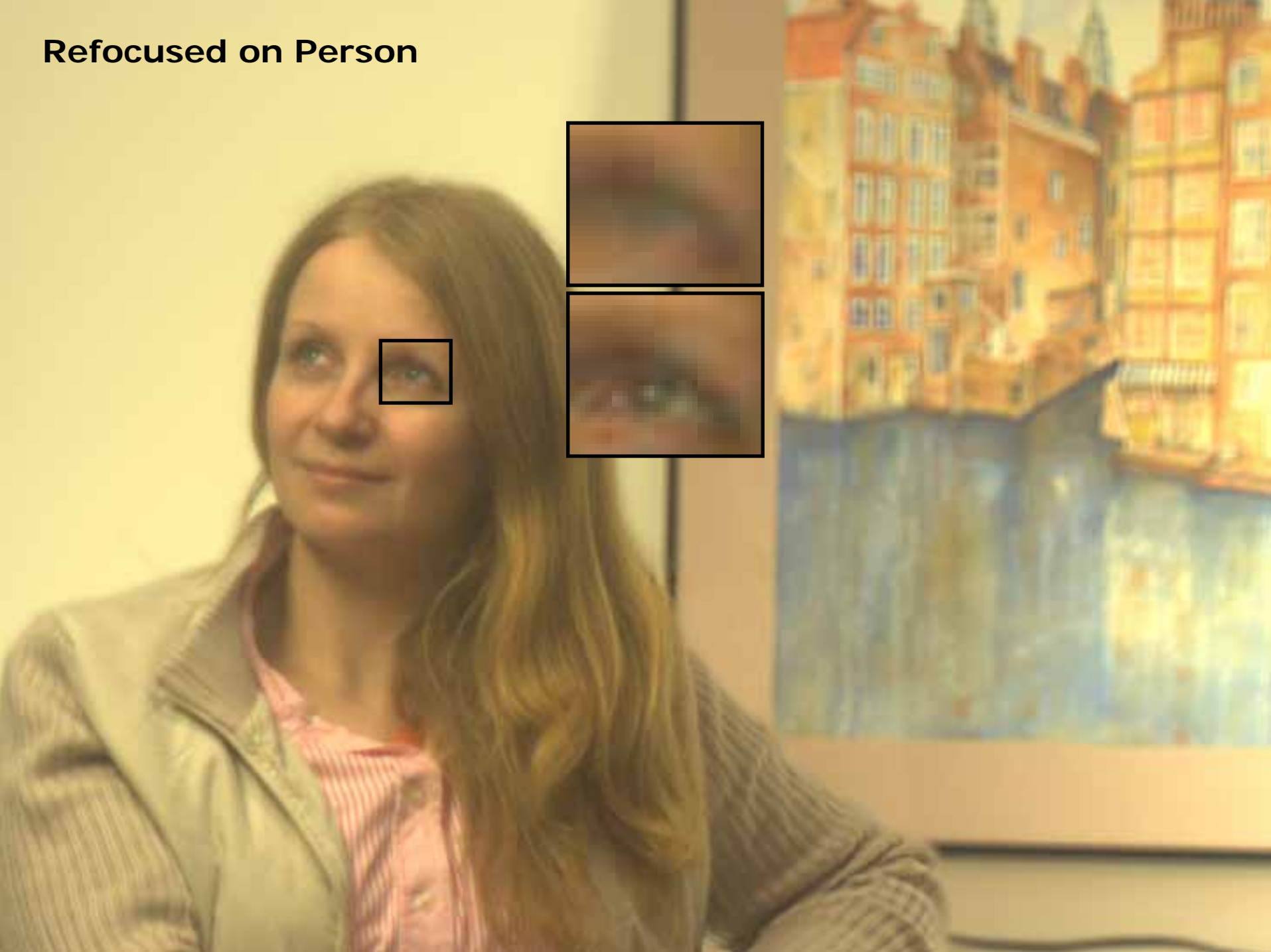


Out of Focus Photo: Coded Aperture

Captured Blurred Photo



Refocused on Person



Digital Refocusing

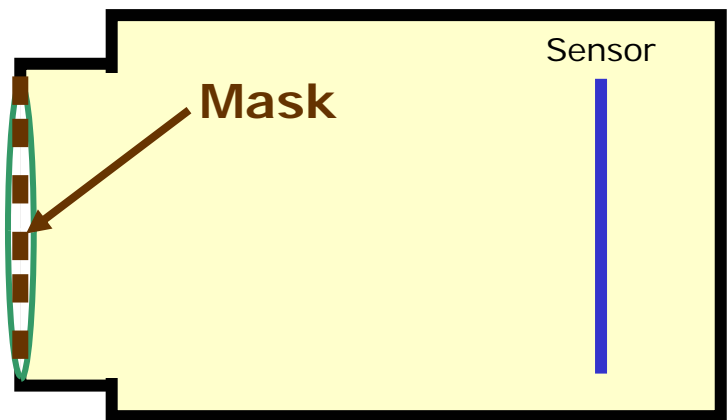
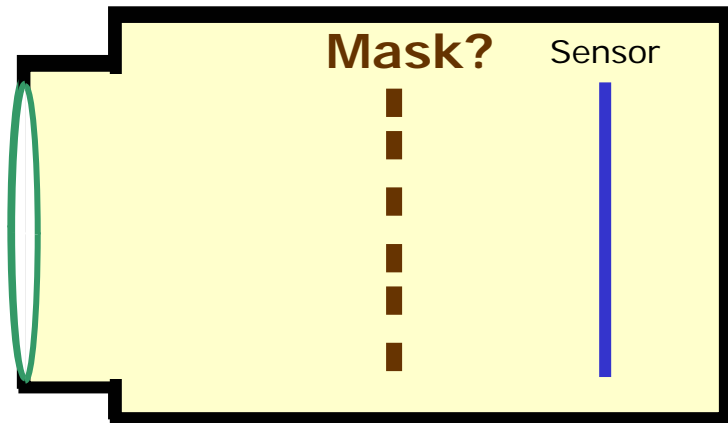


Captured Blurred Photo

Digital Refocusing



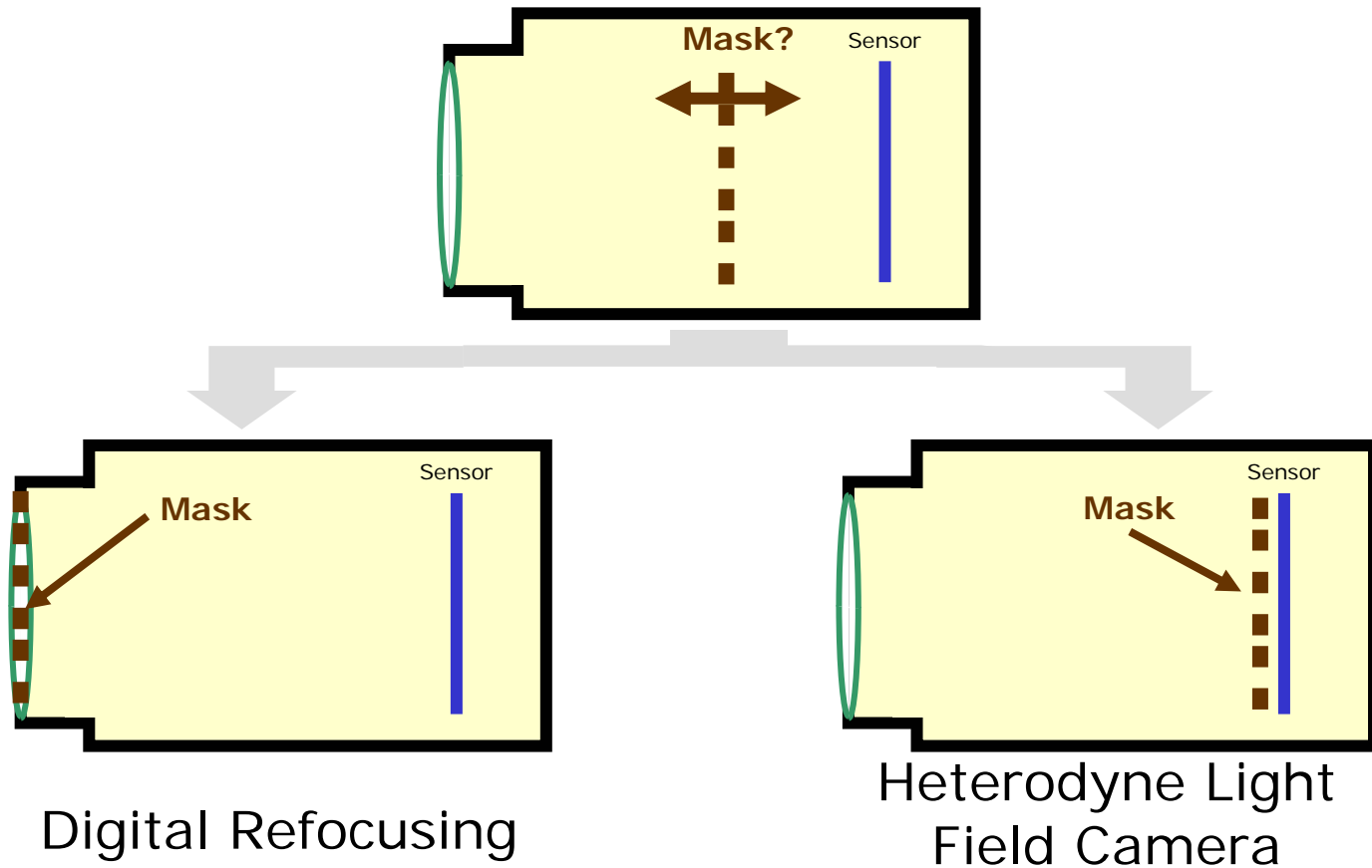
Refocused Image on Person



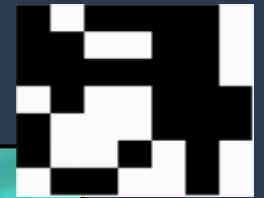
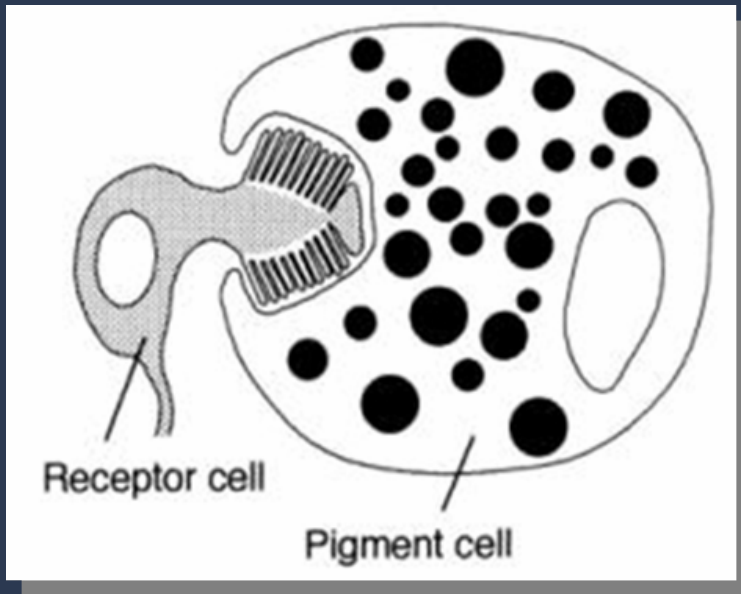
Digital
Refocusing

Heterodyne
Light Field
Camera

Mask = more information?



[Veeraraghavan, Raskar, Agrawal, Tumblin, Mohan],
Siggraph 2007



Larval Trematode Worm

What is Photography?

PHYSICAL

3D Scene

light sources,
BRDFs,
shapes,
positions,
movements,
...

Eyepoint

position,
movement,
projection,
...

Light &
Optics

Exposure
Control,
tone map

Image

$I(x,y,\lambda,t)$

Display

$RGB(x,y,t_n)$

PERCEIVED

Scene

light sources,
BRDFs,
shapes,
positions,
movements,
...

Eyepoint

position,
movement,
projection,
...

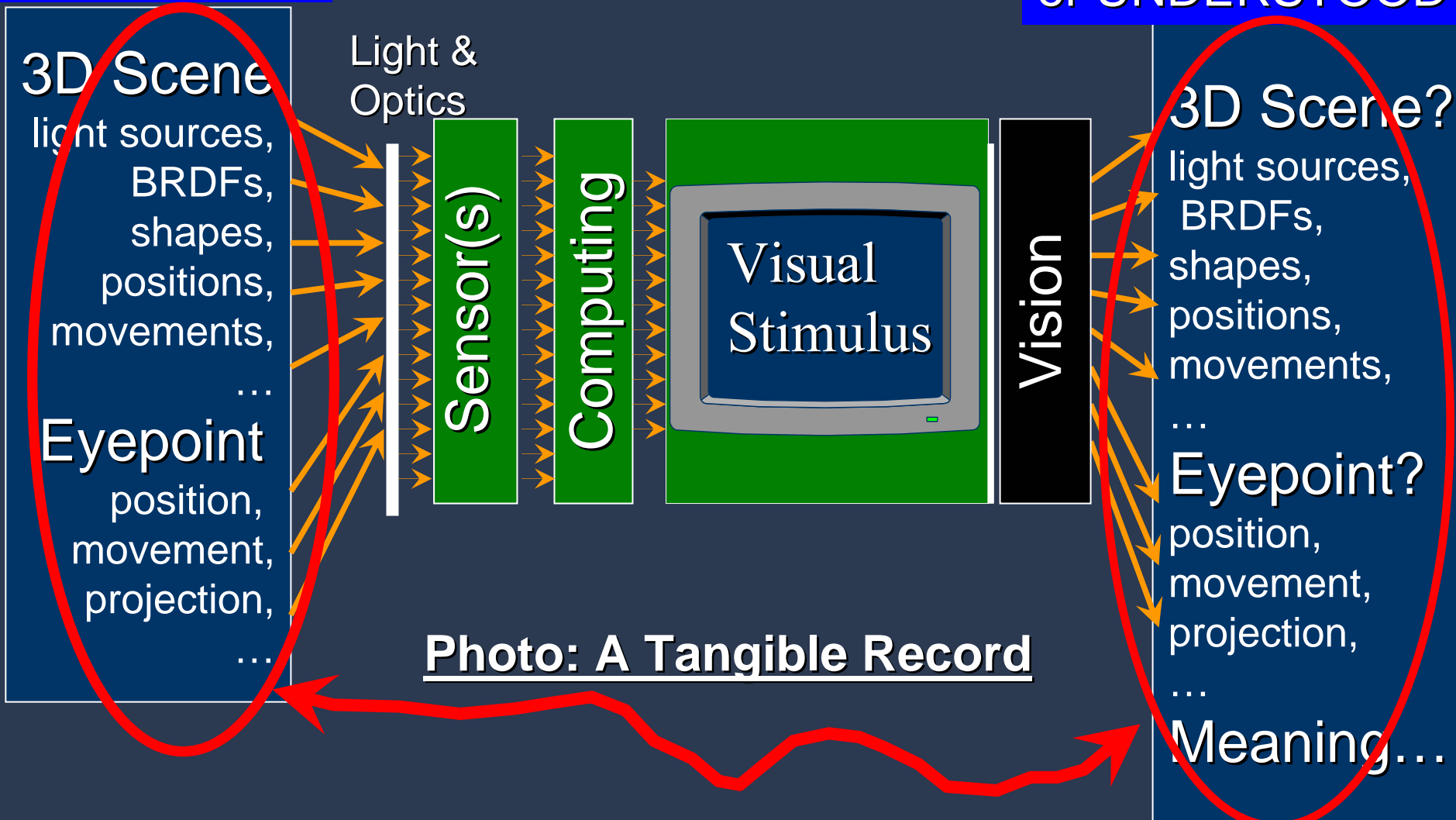
Vision

Photo: A Tangible Record
Editable, storable as
Film or Pixels

Ultimate Photographic Goals

PHYSICAL

PERCEIVED
or UNDERSTOOD



Multiperspective Camera?



[Jingyi Yu' 2004]

Next Class

- Homework
 - How can we augment the camera to support best 'image search'?
 - Search=segment/identify/recognize/transform/compare/archive
 - How can we make the visual experience machine readable? Is this the key problem? 3D reconstruction? Hardware and software solutions? Crowdsourcing? Metadata tagging?
 - Material index/Segmentation/Repeatable view and illumination invariance/
 - Email to [raskar@media.mit..]
- Volunteer
 - Class notes
 - Select/read/present/paper
 - Visual Social Computing
 - Beyond Visible Spectrum
 - Mobile Photography
 - Emerging sensors
 - [Send me email ..]
 - (Extra Credit)

Next Wedn 3pm

Less is More: Coded Computational Photography

Speaker: Ramesh Raskar, Associate Professor, MIT Media Lab

Date: Wednesday, February 20 2008

Time: 3:00PM to 4:00PM

Refreshments: 2:45PM

Location: Star Seminar Room (32-D463)

	Topic	Topic	Guest Speaker
1	Feb 06	Introductions	
2	Wed 13 Feb	Imaging Devices, Modern Optics and Lenses	
3	Wed 20 Feb	Mobile Photography	
4	Wed 27 Feb	Visual Social Computing and Citizen Journalism	Google Maps Streetview (Luc Vincent, TBA)
5	Wed 05 Mar	Emerging Sensor Technologies	Nokia Research, Mobile Computational Photography (TBA)
6	Wed 12 Mar	Beyond Visible Spectrum	RedShift Technologies(Matthias Wagner, Thermal Imaging)
7	Wed 19 Mar		Intel Research (Nehal Sukthankar)
SPRING BREAK			
8	Wed 02 Apr	Trust in Imaging	Microsoft ?
9	Wed 09 Apr	Computational Imaging in Sciences	Canon USA (Consumer Imaging Group) (TBA)
10	Wed 16 Apr	Solutions for Visually Challenged	Sony EyeToy
11	Wed 23 Apr	NO class	
12	Wed 30 Apr	Cameras in Developing Countries Future Products and Business Models	HP Research Labs (Tom Malzbender on CameraPhone Usage, GPS-based tools)
13	Wed 07 May	Student Presentations	
14	Wed 14 May	Student Presentations	